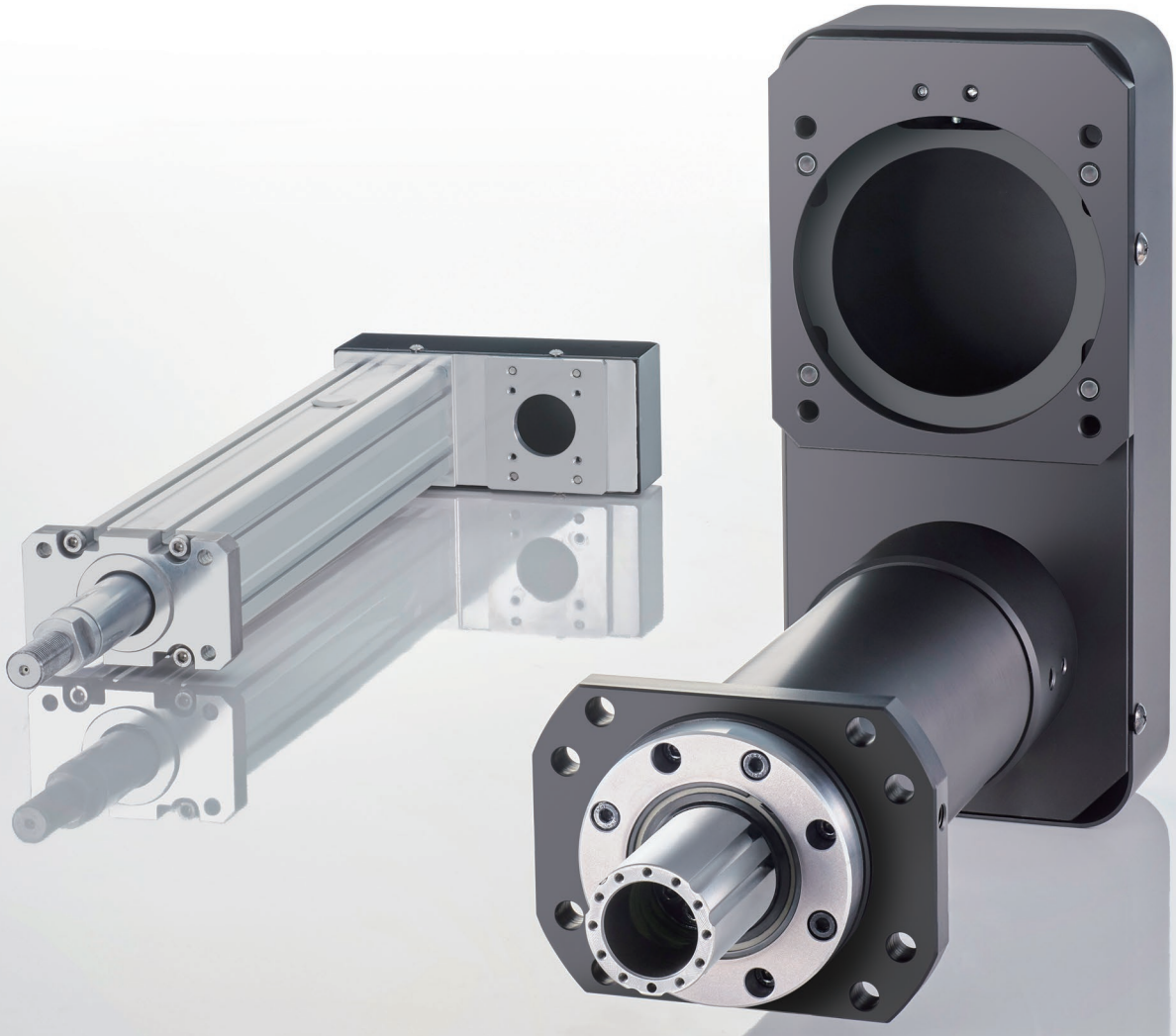
Electric Cylinder

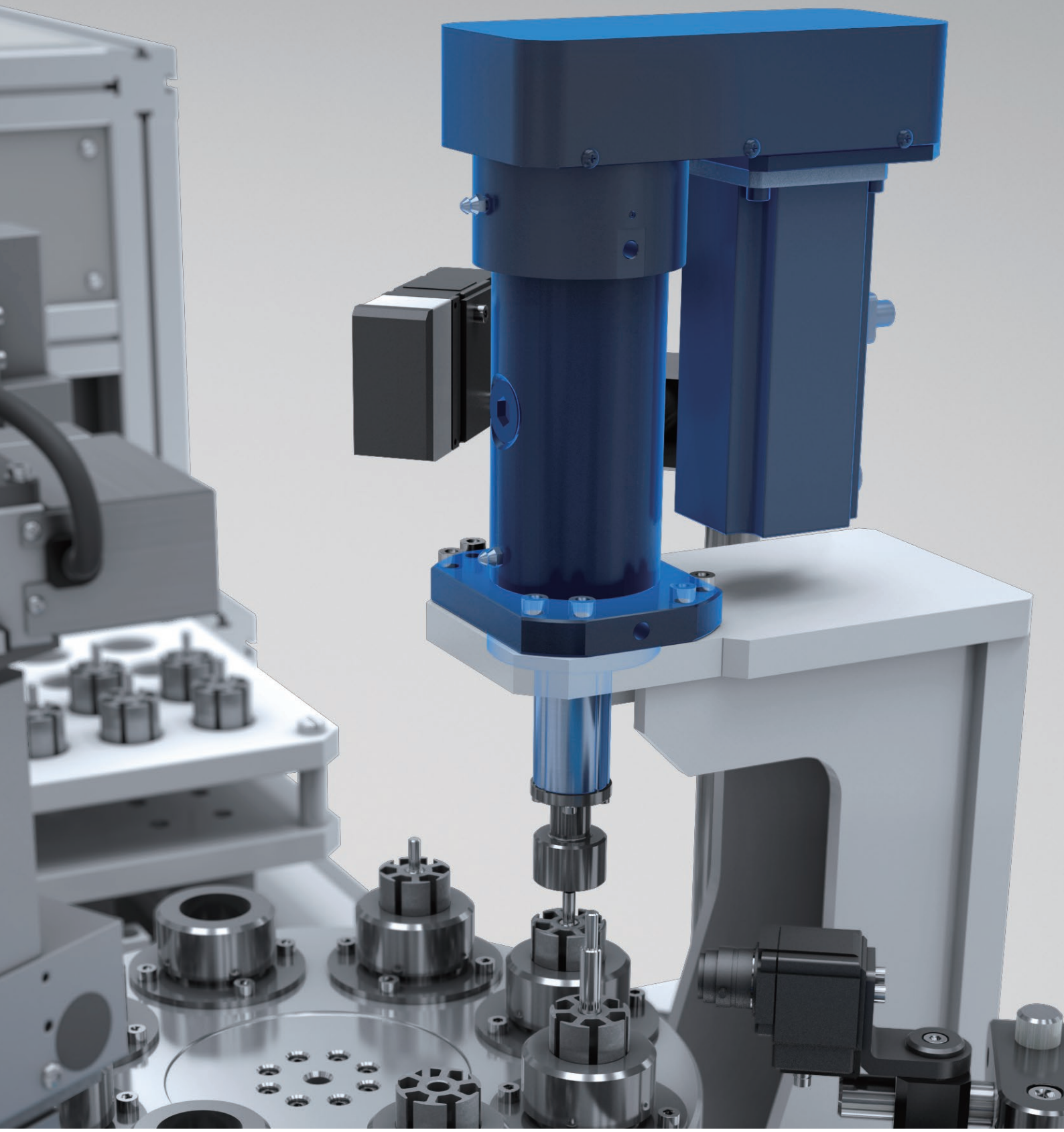
PC/PCT



Maximum instantaneous thrust of 250 kN.
Smooth motion and highly precise positioning repeatability.
Compact design.

High efficiency × Low running cost

Motorization for numerous press processes

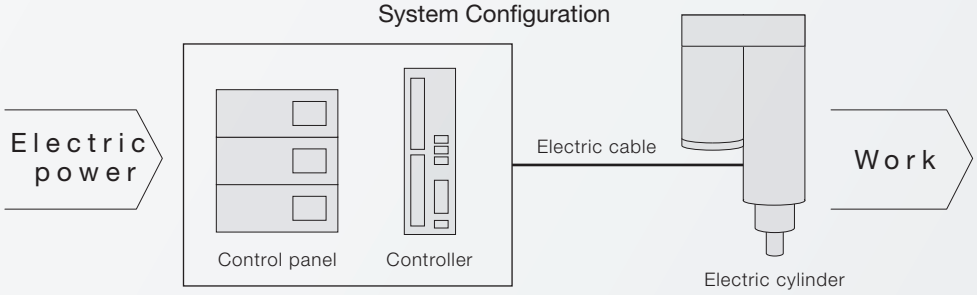


Electric Cylinder

Motorization of the cylinder driver provides five benefits.

Energy savings	Freed-up space	Consistent quality	Reduction of defects	Increased efficiency in equipment inspection process

System Configuration



(Example) Electric and Hydraulic Cylinder Comparison

	Motion control				Machining control			Environment		
Electric	◎	◎	◎	◎	◎	◎	◎	◎	◎	◎
Properties	Ability to select speed	High-speed motion	Ability to select thrust	Bottom dead center position control when molding	High-precision machining	Ability to machine difficult materials	Lower burden on molds	Compact equipment footprint	Clean environment	Quiet noise
Hydraulic	○	○	○	-	-	○	-	-	-	-

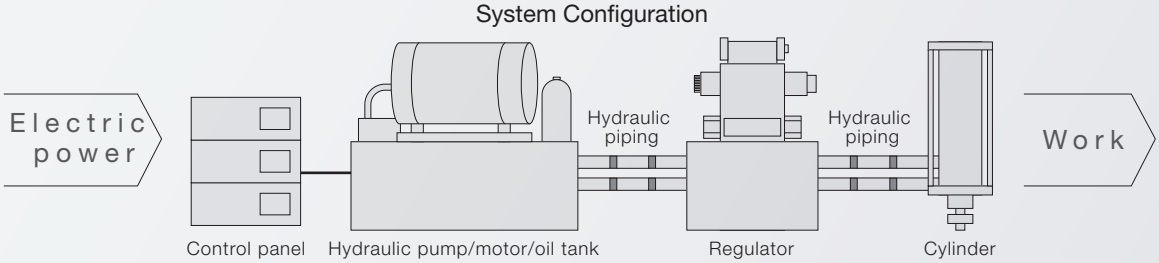
[1] The above is a general comparison.

[2] ◎: Superior, ○: Good, -: Not compatible

Hydraulic Cylinder

Reduced energy efficiency	Constriction of equipment space	Noise and oil leaks	Affected by air temperature	Frequent piping work/ maintenance

System Configuration



Electric Cylinder PC/PCT

Achieves steady, high thrust and high-precision positioning repeatability by using a ball screw for the drive element.

PC

High-thrust electric cylinder
with proprietary, built-in mechanism
combining the drive and guide elements

Compact, highly rigid, high-precision. Can be used in presses that require high thrust.

Space savings are enabled by the compact structure, which combines the ball spline shaft and the high-precision ball screw nut. Furthermore, this product achieves high thrust with a maximum instantaneous thrust of 250 kN* and high-precision positioning repeatability.
It is optimal for high-precision pressing, press-fitting workpieces, punching, and deep drawing.

Smooth movement and high-precision positioning repeatability provided by ball spline and ball screw.

This model is capable of bearing large loads thanks to the maximized ball screw shaft diameter and the increased number of loaded circuits.

Maximum instantaneous thrust
250 kN*
(25 t)

Rated thrust
106 kN*
(10 t)

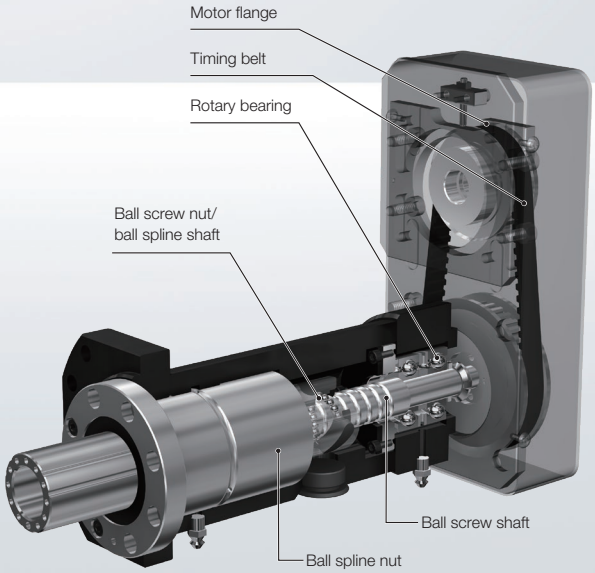
Fewer defects
Consistent quality

* When using PC120

Positioning repeatability > **±0.005 mm**

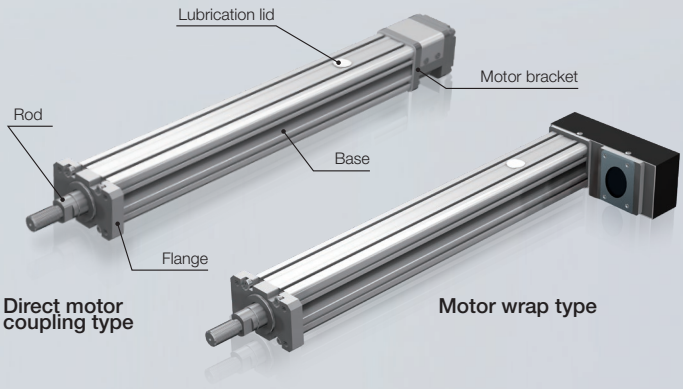
PCT

An electric cylinder
with an internal ball screw



Supports a variety of mounting configurations with two different mounting methods. Enables high-precision positioning repeatability.

Because the PCT is specialized in rigidity for load-bearing in the axial direction, it can be used in small presses and caulking machines.

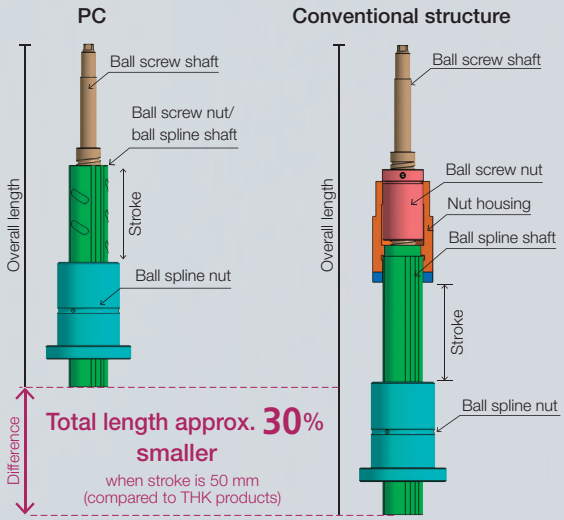


Direct motor coupling type

Motor wrap type

Unique, integrated structure enables compactness.

With an integrated structure combining a ball spline with a precision ball screw, the overall length is significantly more compact, and there are fewer components.



Rated thrust
800 N max.

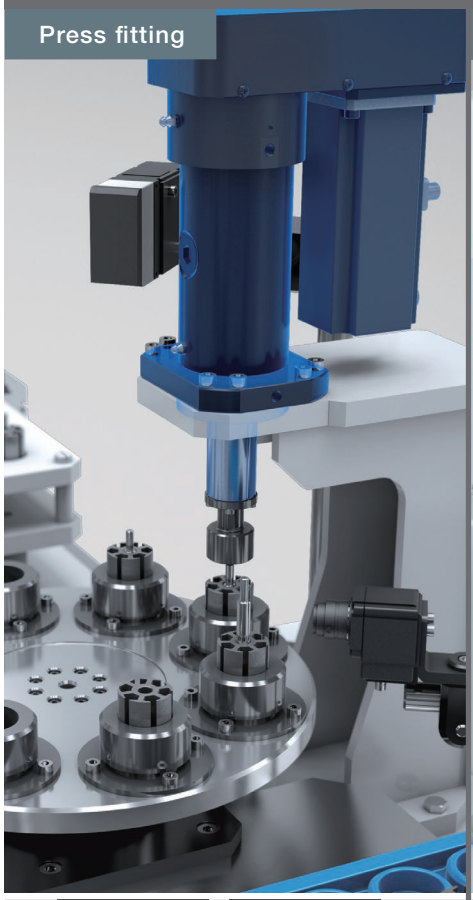
Positioning repeatability **±0.01 mm**

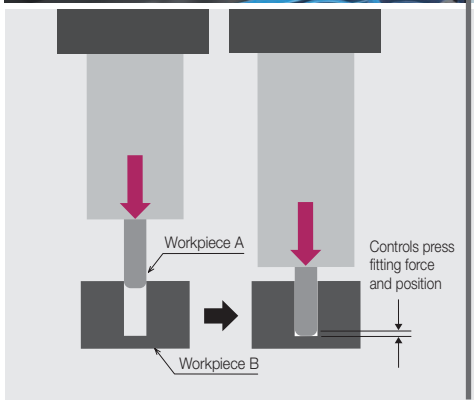
Mount with flange or mount using the T-slot on the main unit.

APPLICATION

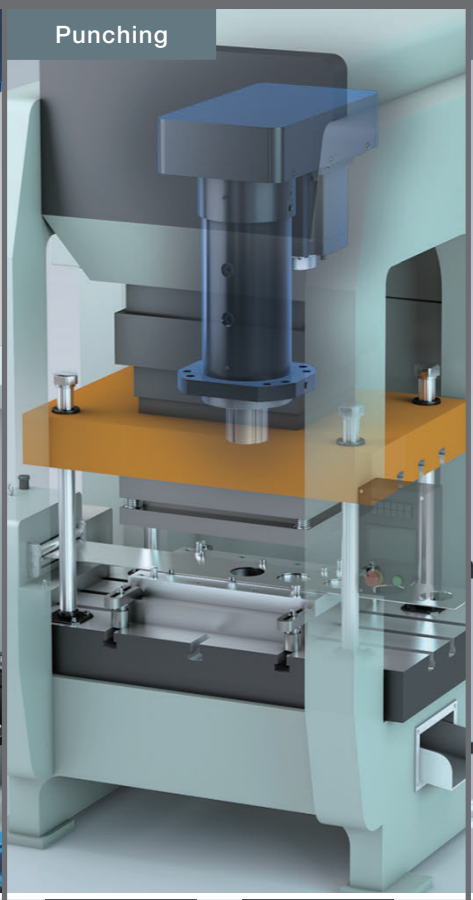
PC

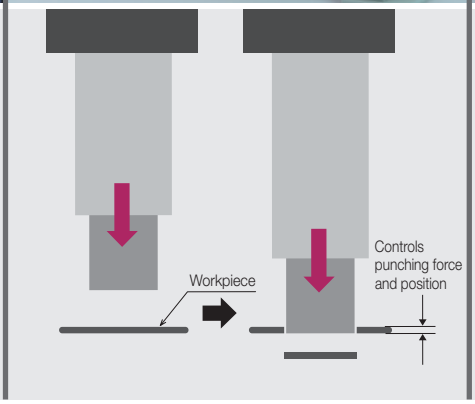
Press fitting



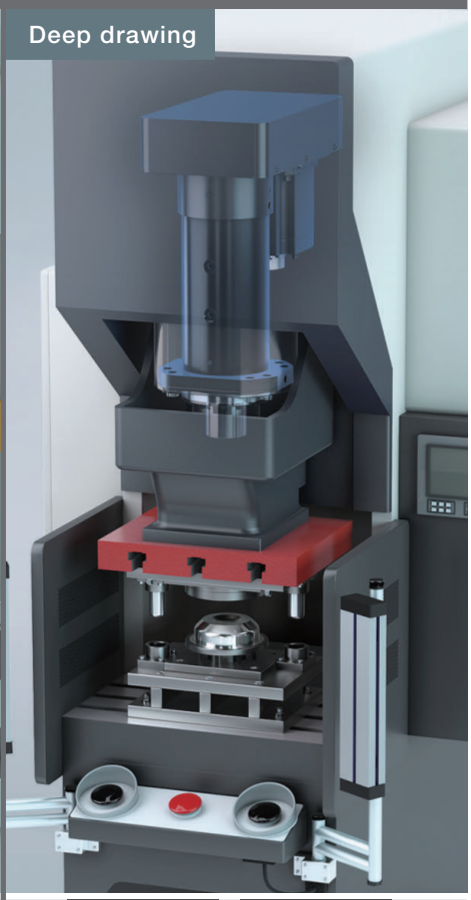


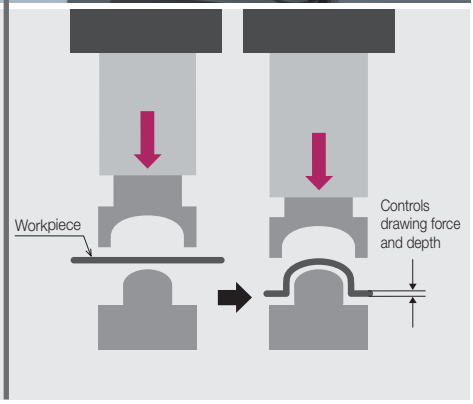
Punching





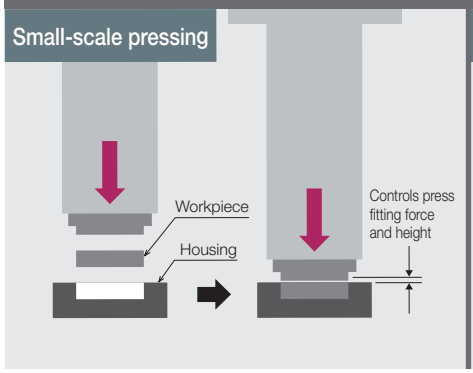
Deep drawing



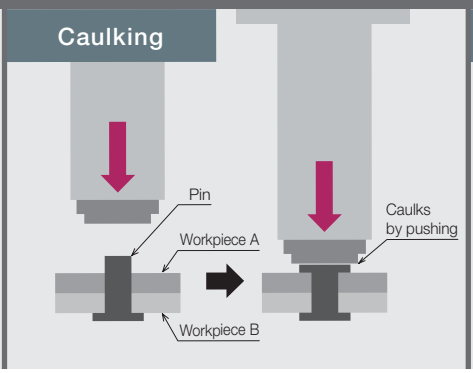


PCT

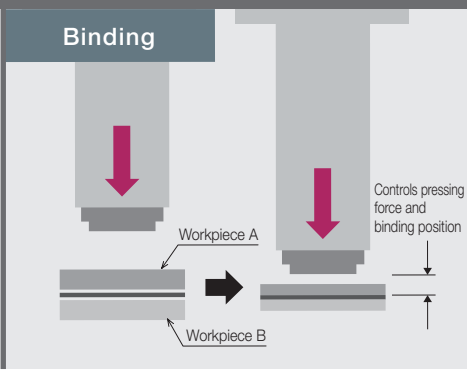
Small-scale pressing



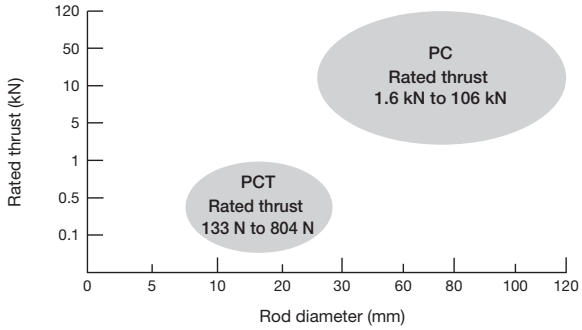
Caulking



Binding



Product Lineup



Specifications

PC

Model	Servo motor		Rated thrust[1] (kN)	Maximum instantaneous thrust[2] (kN)	Maximum speed[3] (mm/s)	Maximum stroke (mm)	Generated thrust[4] (kN)
	Manufacturer	Estimated capacity (kW)					0 1 2 3 7.5 10 15 20 30 40 50 70 100 120 140 160 180 200 220 240
PC30–06A	Mitsubishi Electric Corporation YASKAWA Electric Corporation SANYO DENKI CO., LTD. OMRON Corporation	0.4 (0.36)[5]	1.6	3.3	210	250	1.6 3.3
PC40–06B	Mitsubishi Electric Corporation YASKAWA Electric Corporation SANYO DENKI CO., LTD. OMRON Corporation	0.75	3.2	6.4	200		3.2 6.4
PC40H–08C	Mitsubishi Electric Corporation	1	5.6	11.2	151		5.6 11.2
	YASKAWA Electric Corporation	0.85	6.3		113		6.3
	SANYO DENKI CO., LTD.	1.2	6.7		151		6.7
	OMRON Corporation	1	5.6		150		5.6
PC50–06D	Mitsubishi Electric Corporation	1.5	8.4	16.8	150		8.4 16.8
		1.75	9.9		150		9.9
	YASKAWA Electric Corporation	1.3	9.8		112		9.8
	SANYO DENKI CO., LTD.	1.8	10.2		150		10.2
	OMRON Corporation	1.5	8.4		150		8.4
PC60–10E	Mitsubishi Electric Corporation	2	10.9	21.8	155		10.9 21.8
	YASKAWA Electric Corporation	1.8	13.1		116		13.1
	SANYO DENKI CO., LTD.	2	10.9		155		10.9
	OMRON Corporation	2	10.9		155		10.9
PC60H–10F	Mitsubishi Electric Corporation	3.5	17.8	35.6	166		17.8 35.6
	YASKAWA Electric Corporation	2.9	19.8		125		19.8
	SANYO DENKI CO., LTD.	3.5	18.1		166		18.1
	OMRON Corporation	4	20.4		166		20.4
		4	20.4		125		
PC80L–12G	Mitsubishi Electric Corporation	5	24	71	177		24 71
	YASKAWA Electric Corporation	4.4	28	71	133		28
	SANYO DENKI CO., LTD.	4.5	21	75	177		21 75
	OMRON Corporation	5	23.9	71.7	177		23.9 71.7
		4	25.5	71.7	133		25.5
PC80–12G	Mitsubishi Electric Corporation	7	33	100	177		33 100
	YASKAWA Electric Corporation	5.5	35	102	133		35 102
	SANYO DENKI CO., LTD.	5.5	35	107	133		35
	OMRON Corporation	4.5	43	107	88		43 107
		5	31	107	133		31
PC80H–12G	Mitsubishi Electric Corporation	4.2	40	120	88		40 120
	YASKAWA Electric Corporation	7.5	48	119	133		48 119
	SANYO DENKI CO., LTD.	7.5	48	120	133		48 120
	OMRON Corporation	7.5	47.8	119	133		47.8 119
PC100–20H	Mitsubishi Electric Corporation	11	70	175	125	400	70 175
	YASKAWA Electric Corporation	11	70	175	125		
	SANYO DENKI CO., LTD.	11	70	175	125		
	OMRON Corporation	11	70	175	125		
PC120–20J	Mitsubishi Electric Corporation	15	106	250	112		106 250
	YASKAWA Electric Corporation	15	106	250	112		
	SANYO DENKI CO., LTD.	15	106	240	112		106 240
	OMRON Corporation	15	106	250	112		106 250

Rated thrust / Maximum instantaneous thrust

[1] The rated thrust refers to the thrust force at the rated motor torque for the estimated motor capacity.
[2] Maximum instantaneous thrust is limited by the permissible axial load.
[3] The maximum speed is restricted either by the rated rotational speed for the estimated motor capacity or by the permissible speed of the actuator.
[4] Contact THK if the product will be used for pressing motions above the rated thrust but below the maximum instantaneous thrust.
[5] Value within parentheses is when a SANYO DENKI CO., LTD. motor with a brake is used.

PCT

Model	Estimated motor capacity (W)	Rated thrust[6] (N)	Maximum speed[7] (mm/s)	Maximum stroke (mm)	Generated thrust[8] (N)
					0 100 250 500 1000 1500 2500
PCT20–06N	50	133	300	200	130 402
PCT20R–06N					
PCT25–06N	100	266		300	260 796
PCT25R–06N					
PCT25–04N		400	200		400 1194
PCT25R–04N					
PCT25–06N	200	536	300		500 1600
PCT25R–06N					
PCT25–04N		804	200		800 2400
PCT25R–04N					

Rated thrust / Maximum instantaneous thrust

[6] The rated thrust refers to the thrust force at the rated motor torque for the estimated motor capacity.
[7] The maximum speed is restricted either by the rotational speed of the motor at 3000 min^{-1} or by the permissible speed of the actuator.
[8] Contact THK if the product will be used for pressing motions above the rated thrust but below the maximum instantaneous thrust.
Note) See the page of each model for details concerning specifications.

PC Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Design symbol ④	Option (Lubrication Site) ⑤	Compatible motor bracket ⑥
PC30	– 06A	– 0200	– A	– R	– 0M
PC30	06A	0050: 50 mm	A	D: Bottom	0M: Without motor
PC40	06B	to		L: Left	0Y: Without motor
PC40H	06D	0400: 400 mm		R: Right	0S: Without motor
PC50	08C				0R: Without motor
PC60	10E				
PC60H	10F				
PC80L	12G				
PC80	20H				
PC80H	20J				
PC100					
PC120					

This symbol indicates the lead and reduction ratio. Please select from the below combination options.

The maximum stroke varies depending on the model.
PC30 to PC80H: 250 mm
PC100, PC120: 400 mm

This symbol indicates the compatible motor. The character at the end of the symbol (M, Y, S, or R) indicates the motor manufacturer.
M: Mitsubishi Electric Corporation,
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

The mounting components (motor mounting plate, keyless bushing, timing pulley, and timing belt) for each model's compatible motors (p. 9) are included.
When PC100 or PC120 is selected, the product will be shipped with the reduction gear installed.
→ p. 29, 31

Combination Options

Model ①	Lead, reduction ratio ②	Stroke ③	Design symbol ④
PC30	06A	0050 to 0250	A
PC40	06B		
PC40H	08C		
PC50	06D		
PC60	10E		
PC60H	10F		
PC80L	12G		
PC80			
PC80H			
PC100	20H	0200, 0400	
PC120	20J		

PCT Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Options ④	With/without motor ⑤	Motor bracket ⑥	Motor shaft securing method ⑦
PCT20R	06N	0200	R	0	A1	D
PCT20	04N	0050: 50 mm	With direct coupling	0: Without motor	A1	With direct coupling
PCT20R	06N	to	N: Direct coupling		A2	No symbol
PCT25		0300: 300 mm	With motor wrap		K1	With motor wrap
PCT25R			D: Bottom		K2	D: Flat
			L: Left		B1	K: Key
			R: Right		B2	S: Clamp

"R" indicates motor wrap.

This symbol indicates the lead and reduction ratio. For motor wrap specification, only a 1/1 reduction ratio is available. Please select from the below combination options.

For direct motor coupling, select "N." For motor wrap, specify the wrap direction based on the figure below.

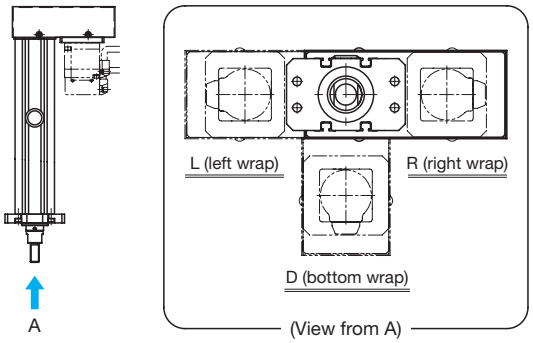
Direct motor coupling specification: No coupling will be included. Please specify if a coupling is required when ordering.
Motor wrap specification: Timing pulley and timing belt will be included. Selections must also be made for ⑥ Motor bracket and ⑦ Motor shaft securing method.

Select the motor bracket from the "Motor Bracket and Motor Shaft Securing Method Chart" that corresponds to the motor selected.

Combination Options

Model ①	Lead, reduction ratio ②	Stroke ③
PCT20 PCT20R	06N	0050 to 0200
PCT25 PCT25R	06N or 04N	0050 to 0300

④ Option (Motor Wrap)



Compatible Motors (Control Devices) by Model List

Model, lead, reduction ratio	Manufacturer		Motor model	Motor rated output (kW)	Compatible motor bracket[1]
PC30–06A	Mitsubishi Electric Corporation	Without brake	HG–KR43	0.4	0M
		With brake	HG–KR43B		
		Without brake	HK–KT43W		
		With brake	HK–KT43WB		
	YASKAWA Electric Corporation	Without brake	SGM7J–04AFA21	0.4	0Y
		With brake	SGM7J–04AFA2C		
		Without brake	SGMXJ–04AWA21A1		
		With brake	SGMXJ–04AWA2CA1		
	SANYO DENKI CO., LTD.	Without brake	R2AA06040FXRA0M	0.4	0S
		With brake	R2AA06040FCRA0M6		
	OMRON Corporation	Without brake	R88M–K40030T	0.4	0R
		With brake	R88M–K40030T–B		
		Without brake	R88M–1M40030T		
		With brake	R88M–1M40030T–B		
PC40–06B	Mitsubishi Electric Corporation	Without brake	HG–KR73	0.75	0M
		With brake	HG–KR73B		
		Without brake	HK–KT7M3W		
		With brake	HK–KT7M3WB		
	YASKAWA Electric Corporation	Without brake	SGM7J–08AFA21	0.75	0Y
		With brake	SGM7J–08AFA2C		
		Without brake	SGMXJ–08AWA21A1		
		With brake	SGMXJ–08AWA2CA1		
	SANYO DENKI CO., LTD.	Without brake	R2AA08075FXRA0M	0.75	0S
		With brake	R2AA08075FCRA0M		
	OMRON Corporation	Without brake	R88M–K75030T	0.75	0R
		With brake	R88M–K75030T–B		
		Without brake	R88M–1M75030T		
		With brake	R88M–1M75030T–B		
PC40H–08C	Mitsubishi Electric Corporation	Without brake	HG–SR102	1	0M
		With brake	HG–SR102B		
		Without brake	HK–ST102W		
		With brake	HK–ST102WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–09AFA21	0.85	0Y
		With brake	SGM7G–09AFA2C		
		Without brake	SGMXG–09AWA21A1		
		With brake	SGMXG–09AWA2CA1		
	SANYO DENKI CO., LTD.	Without brake	R2AA13120BXRC0[2]	1.2	0S
		With brake	R2AA13120BCRC0[2]		
	OMRON Corporation	Without brake	R88M–K1K020T	1	0R
		With brake	R88M–K1K020T–B		
		Without brake	R88M–1M1K020T		
		With brake	R88M–1M1K020T–B		
PC50–06D	Mitsubishi Electric Corporation	Without brake	HG–SR152	1.5	0M
		With brake	HG–SR152B		
		Without brake	HK–ST172W	1.75	0M
		With brake	HK–ST172WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–13AFA21	1.3	0Y
		With brake	SGM7G–13AFA2C		
		Without brake	SGMXG–13AWA21A1		
		With brake	SGMXG–13AWA2CA1		
	SANYO DENKI CO., LTD.	Without brake	R2AA13180HXRC0[2]	1.8	0S
		With brake	R2AA13180HCRC0[2]		
	OMRON Corporation	Without brake	R88M–K1K520T	1.5	0R
		With brake	R88M–K1K520T–B		
		Without brake	R88M–1M1K520T		
		With brake	R88M–1M1K520T–B		
PC60–10E	Mitsubishi Electric Corporation	Without brake	HG–SR202	2	0M
		With brake	HG–SR202B		
		Without brake	HK–ST202W		
		With brake	HK–ST202WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–20AFA21	1.8	0Y
		With brake	SGM7G–20AFA2C		
		Without brake	SGMXG–20AWA21A1		
		With brake	SGMXG–20AWA2CA1		
	SANYO DENKI CO., LTD.	Without brake	R2AA13200LXRC0[2]	2	0S
		With brake	R2AA13200LCRC0[2]		
	OMRON Corporation	Without brake	R88M–K2K020T	2	0R
		With brake	R88M–K2K020T–B		
		Without brake	R88M–1M2K020T		
		With brake	R88M–1M2K020T–B		

[1] The character at the end of the symbol (M, Y, S, or R) represents the motor manufacturer. M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; R: OMRON Corporation

[2] Special product for PC specification.

Note) The table shows only a portion of the model numbers for motors. For details regarding model numbers, please see the catalog for each respective motor manufacturer.

Model, lead, reduction ratio	Manufacturer		Motor model	Motor rated output (kW)	Compatible motor bracket[1]
PC60H–10F	Mitsubishi Electric Corporation	Without brake	HG–SR352	3.5	0M
		With brake	HG–SR352B		
		Without brake	HK–ST352W		
		With brake	HK–ST352WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–30AFA21	2.9	0Y
		With brake	SGM7G–30AFA2C		
	SANYO DENKI CO., LTD.	Without brake	R2AA18350LXRC0[2]	3.5	0S
		With brake	R2AA18350LCRC0[2]		
	OMRON Corporation	Without brake	R88M–K4K020T	4	0R
		With brake	R88M–K4K020T–B		
		Without brake	R88M–1M4K015T		
		With brake	R88M–1M4K015T–B		
PC80L–12G	Mitsubishi Electric Corporation	Without brake	HG–SR502	5	0M
		With brake	HG–SR502B		
		Without brake	HK–ST502W		
		With brake	HK–ST502WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–44AFA21	4.4	0Y
		With brake	SGM7G–44AFA2C		
	SANYO DENKI CO., LTD.	Without brake	R2AA18450HXRC0[2]	4.5	0S
		With brake	R2AA18450HCRC0[2]		
	OMRON Corporation	Without brake	R88M–K5K020T	5	0R
		With brake	R88M–K5K020T–B		
		Without brake	R88M–1M4K015T	4	0R
		With brake	R88M–1M4K015T–B		
PC80–12G	Mitsubishi Electric Corporation	Without brake	HG–SR702	7	0M
		With brake	HG–SR702B		
		Without brake	HK–ST702W		
		With brake	HK–ST702WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–55AFA21	5.5	0Y
		With brake	SGM7G–55AFA2C		
	SANYO DENKI CO., LTD.	Without brake	R2AA18550HXRC0[2]	5.5	0S
		With brake	R2AA18550HCRC0[2]		
	OMRON Corporation	Without brake	R88M–K4K510T	4.5	0R
		With brake	R88M–K4K510T–B		
		Without brake	R88M–1M5K015T	5	0R
		With brake	R88M–1M5K015T–B		
PC80H–12G	Mitsubishi Electric Corporation	Without brake	HG–SR421	4.2	0M
		With brake	HG–SR421B		
		Without brake	HK–ST7024W		
		With brake	HK–ST7024WB		
	YASKAWA Electric Corporation	Without brake	SGM7G–75AFA21	7.5	0Y
		With brake	SGM7G–75AFA2C		
	SANYO DENKI CO., LTD.	Without brake	R2AA18750HXRC0[2]	7.5	0S
		With brake	R2AA18750HCRC0[2]		
	OMRON Corporation	Without brake	R88M–K7K515T	7.5	0R
		With brake	R88M–K7K515T–B		
		Without brake	R88M–1M7K515T		
		With brake	R88M–1M7K515T–B		
PC100–20H	Mitsubishi Electric Corporation	Without brake	HG–JR11K1M	11	0M
		With brake	HG–JR11K1MB		
	YASKAWA Electric Corporation	Without brake	SGM7G–1AAFA21	11	0Y
		With brake	SGM7G–1AAFA2C		
	SANYO DENKI CO., LTD.	Without brake	R2AA2211KBXRC0[2]	11	0S
		With brake	R2AA2211KBCRC0[2]		
	OMRON Corporation	Without brake	R88M–1M11K015T	11	0R
		With brake	R88M–1M11K015T–B		
PC120–20J	Mitsubishi Electric Corporation	Without brake	HG–JR15K1M	15	0M
		With brake	HG–JR15K1MB		
	YASKAWA Electric Corporation	Without brake	SGM7G–1EAFA21	15	0Y
		With brake	SGM7G–1EAFA2C		
	SANYO DENKI CO., LTD.	Without brake	R2AA2215KBXRC0[2]	15	0S
		With brake	R2AA2215KBCRC0[2]		
	OMRON Corporation	Without brake	R88M–1M15K015T	15	0R
		With brake	R88M–1M15K015T–B		

[1] The character at the end of the symbol (M, Y, S, or R) represents the motor manufacturer. M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; R: OMRON Corporation

[2] Special product for PC specification.

Note) The table shows only a portion of the model numbers for motors. For details regarding model numbers, please see the catalog for each respective motor manufacturer.

PC30–06A

Rod diameter 30 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC30	–	06A	–	0200	A	–	R	–	0M
PC30		06A		0050: 50 mm	A		D: Bottom		0M: Without motor
				to			L: Left		0Y: Without motor
				0250: 250 mm			R: Right		0S: Without motor
									0R: Without motor

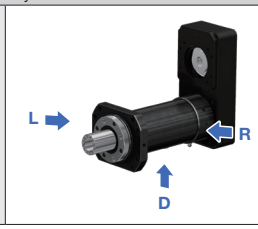
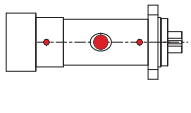
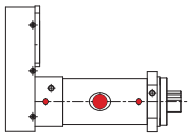
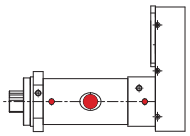
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

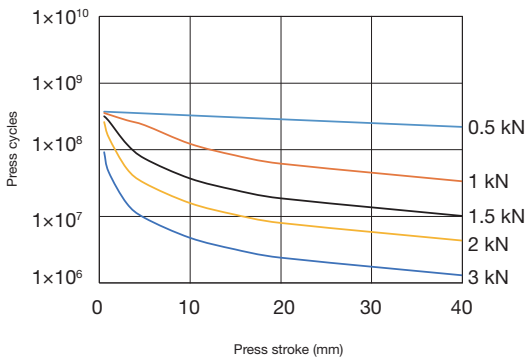
Selection Information

Basic Specifications

Ball screw lead (mm)		6
Reduction ratio		28/40
Permissible axial load[1] (kN)	Pressing direction	3.3
	Pulling direction	1.6
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		2, 6
Maximum load capacity[3] (kg)		15

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

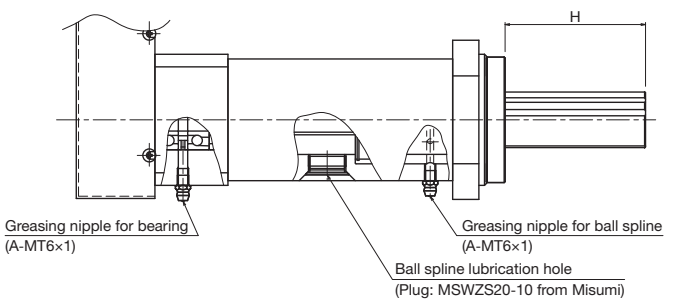


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

Maintenance

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.
Lubricate the product with the rod extended to the lubrication site.

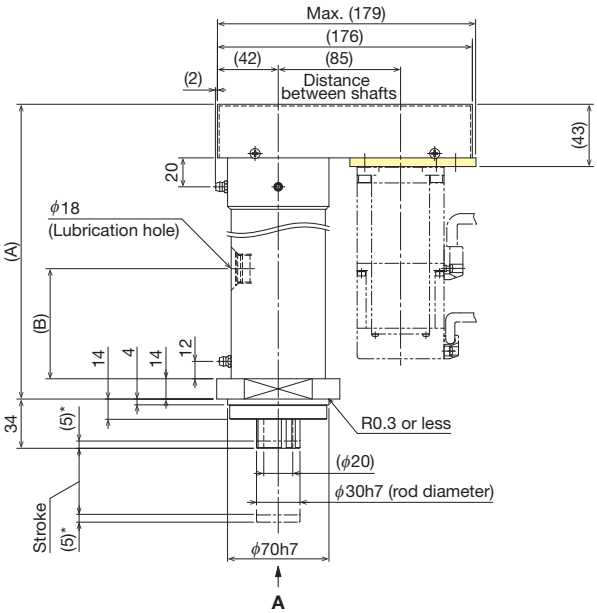


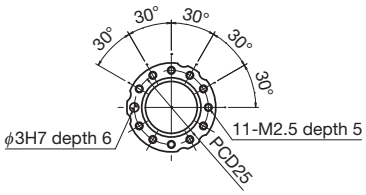
Unit: mm

Stroke	50	100	150	200	250
Lubrication site: H	65	102	102	102	103

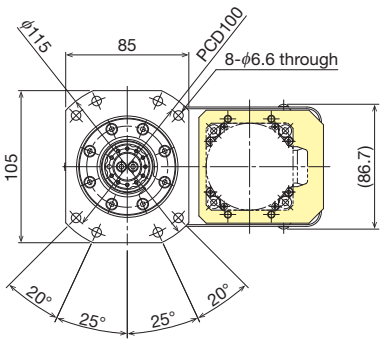
Dimensions

This figure shows lubrication site D (bottom).

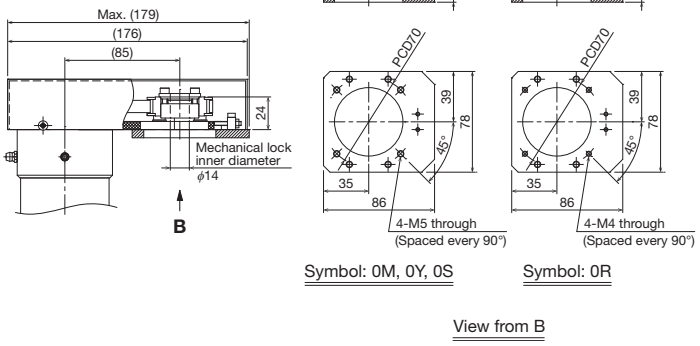




Ball spline shaft end details (view from A)



Motor Attachment Details



Symbol: 0M, 0Y, 0S

Symbol: 0R

View from B

* This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	203.5	253.5	303.5	353.5	403.5
	B	67	80	130	180	230
Mass (kg)		6.9	8	9.2	10.3	11.4

PC40–06B

Rod diameter 40 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC40	–	06B	–	0200	A	–	R	–	0M
PC40		06B		0050: 50 mm	A		D: Bottom		0M: Without motor
				to			L: Left		0Y: Without motor
				0250: 250 mm			R: Right		0S: Without motor
									0R: Without motor

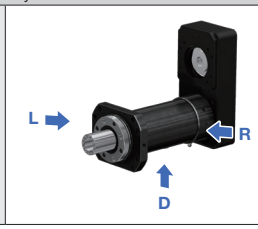
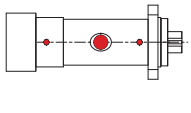
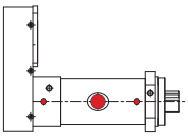
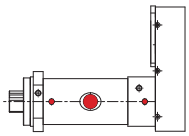
Compatible Motor Bracket Symbol Coding

0 Y

Without motor

M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

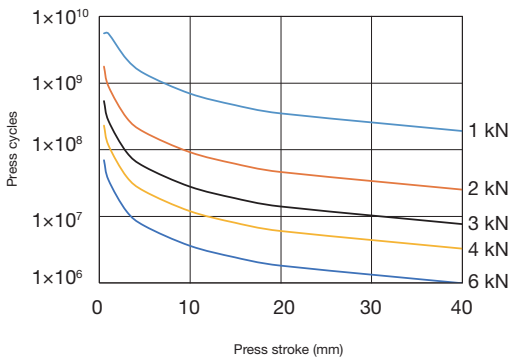
Selection Information

Basic Specifications

Ball screw lead (mm)		6
Reduction ratio		32/48
Permissible axial load[1] (kN)	Pressing direction	6.4
	Pulling direction	3.2
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		4.8
Maximum load capacity[3] (kg)		25

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

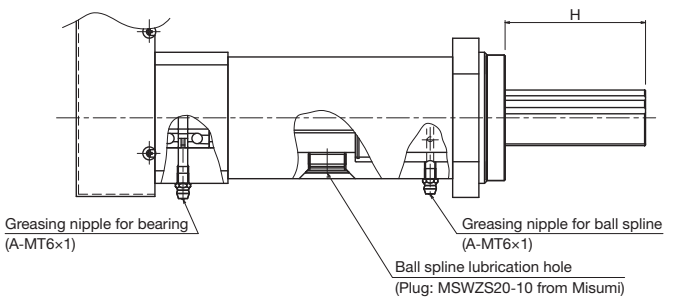


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

Maintenance

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.
Lubricate the product with the rod extended to the lubrication site.

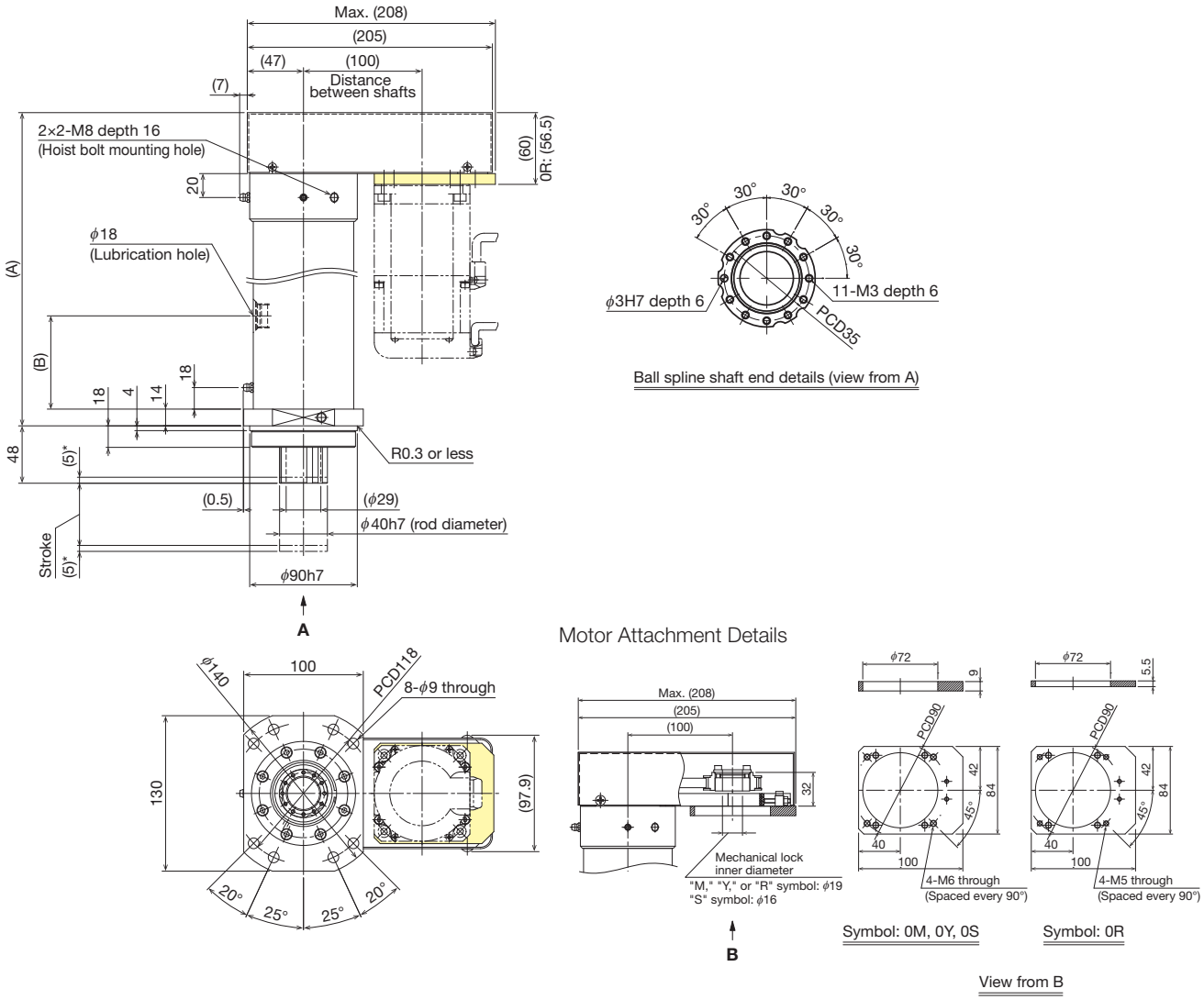


Unit: mm

Stroke	50	100	150	200	250
Lubrication site: H	75	115	115	115	115

Dimensions

This figure shows lubrication site D (bottom).



* This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	237	287	337	387	437
	B	83	93	143	193	243
Mass (kg)		12.3	13.9	15.5	17.1	18.7

PC40H–08C

Rod diameter 40 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Design symbol ④	Option (Lubrication Site) ⑤	Compatible motor bracket ⑥
PC40H	08C	0200	A	R	0M
PC40H	08C	0050: 50 mm	A	D: Bottom	0M: Without motor
		to		L: Left	0Y: Without motor
		0250: 250 mm		R: Right	0S: Without motor
					0R: Without motor

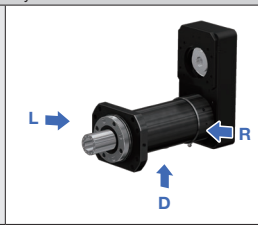
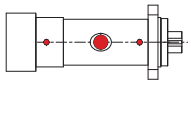
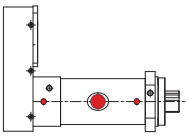
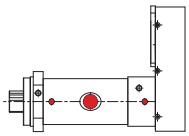
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

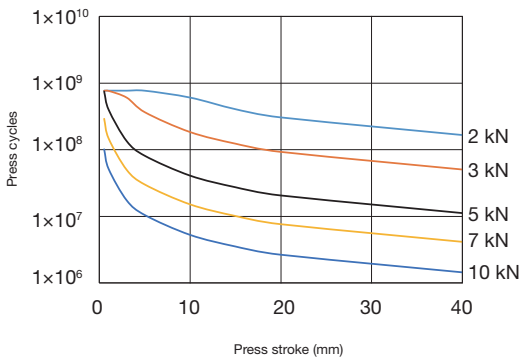
Selection Information

Basic Specifications

Ball screw lead (mm)		8
Reduction ratio		25/44
Permissible axial load[1] (kN)	Pressing direction	11.2
	Pulling direction	5.6
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		9.5
Maximum load capacity[3] (kg)		50

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

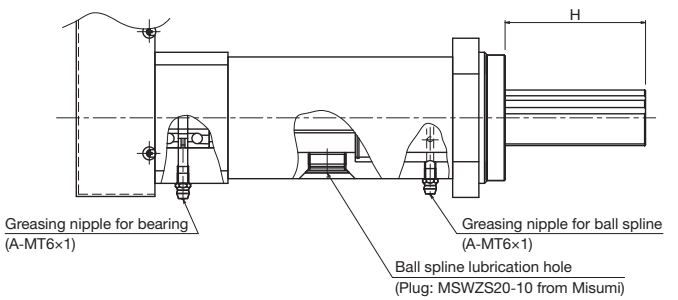


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

Maintenance

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.
Lubricate the product with the rod extended to the lubrication site.

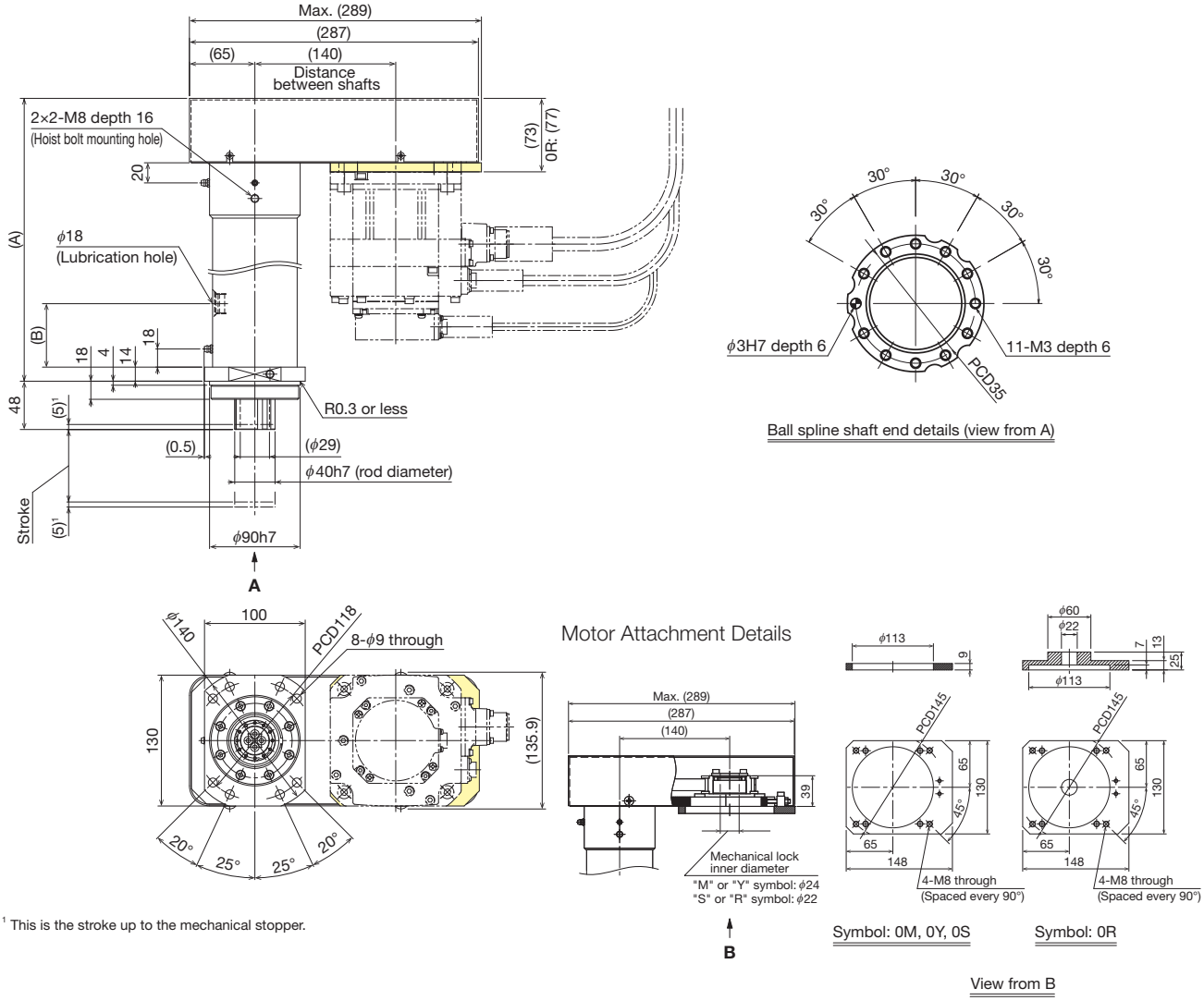


Unit: mm

Stroke	50	100	150	200	250
Lubrication site: H	78	118	148	148	148

Dimensions

This figure shows lubrication site D (bottom).



[1] This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	271	321	371	421	471
	B	83	93	113	163	213
Mass[2] (kg)	0M, 0Y, 0S	17.1	18.7	20.3	21.9	23.5
	0R	18	19.6	21.2	22.8	24.4

[2] The final character of the symbol indicates the manufacturer. Respectively, M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; and R: OMRON Corporation.

PC50–06D

Rod diameter 50 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC50	–	06D	–	0200	A	–	R	–	0M
PC50		06D		0050: 50 mm	A		D: Bottom		0M: Without motor
				to			L: Left		0Y: Without motor
				0250: 250 mm			R: Right		0S: Without motor
									0R: Without motor

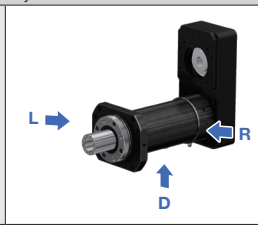
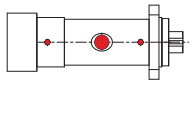
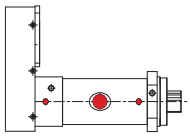
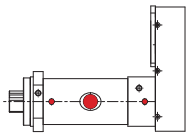
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

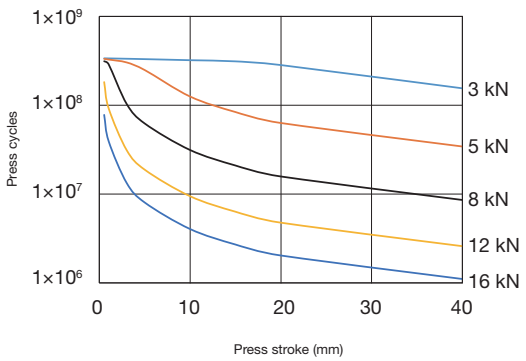
Selection Information

Basic Specifications

Ball screw lead (mm)		6
Reduction ratio		30/40
Permissible axial load[1] (kN)	Pressing direction	16.8
	Pulling direction	8.4
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		14.3
Maximum load capacity[3] (kg)		75

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

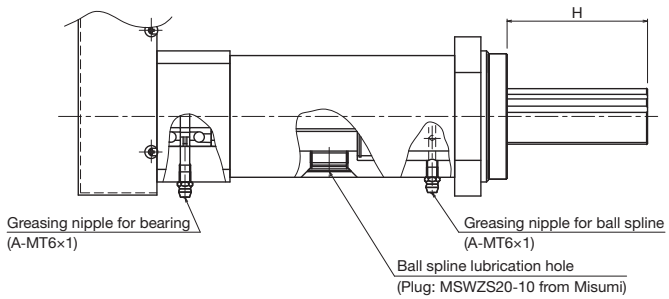


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

Maintenance

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.
Lubricate the product with the rod extended to the lubrication site.

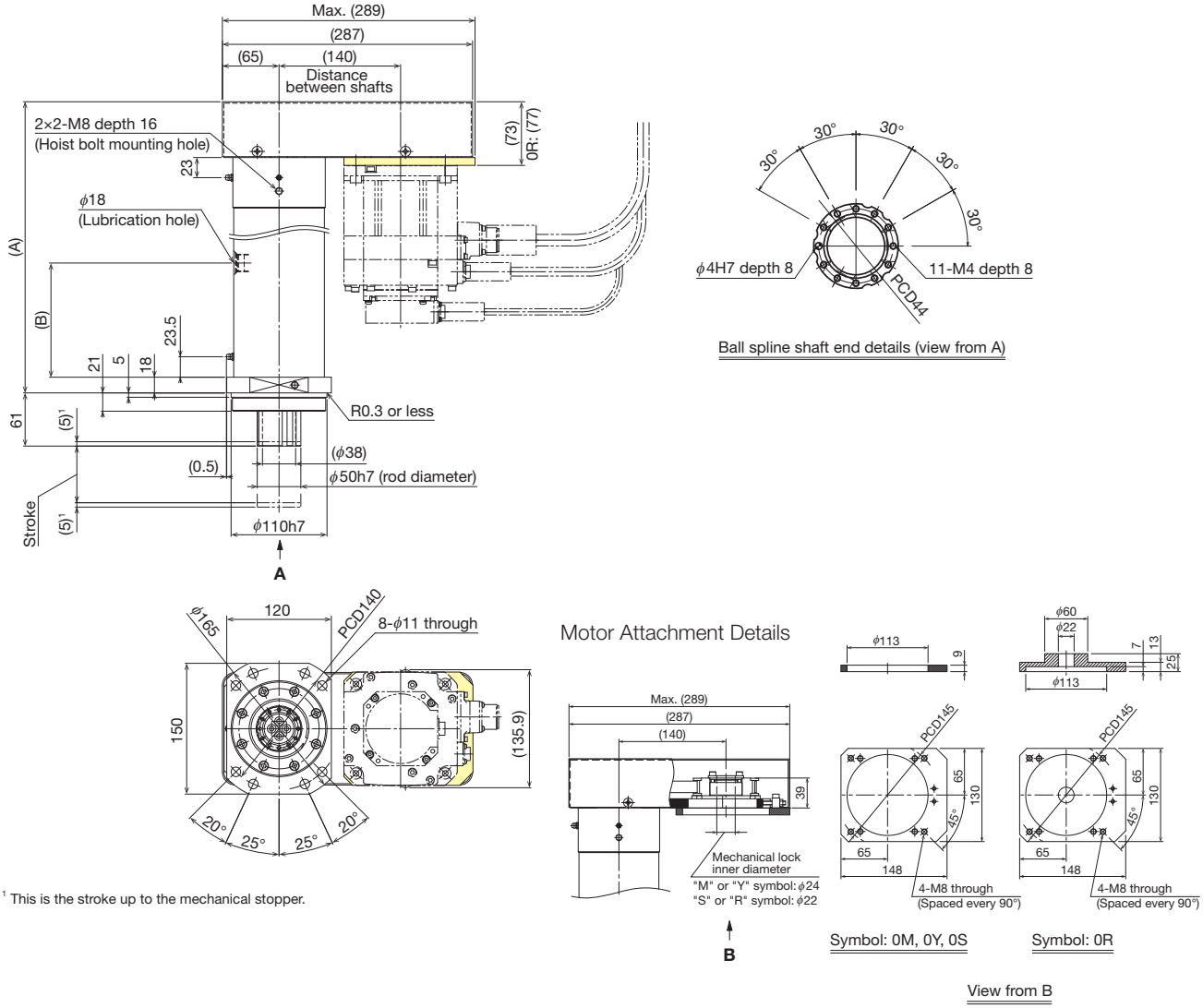


Unit: mm

Stroke	50	100	150	200	250
Lubrication site: H	83	133	173	173	173

Dimensions

This figure shows lubrication site D (bottom).



[1] This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	294	344	394	444	494
	B	101		111	161	211
Mass[2] (kg)	0M, 0Y, 0S	24.5	27.1	29.7	32.2	34.8
	0R	25.4	28	30.6	33.1	35.7

[2] The final character of the symbol indicates the manufacturer. Respectively, M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; and R: OMRON Corporation.

PC60–10E

Rod diameter 60 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC60	–	10E	–	0200	A	–	R	–	0M
PC60		10E		0050: 50 mm	A		D: Bottom		0M: Without motor
				to			L: Left		0Y: Without motor
				0250: 250 mm			R: Right		0S: Without motor
									0R: Without motor

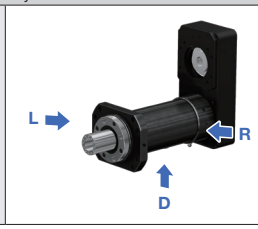
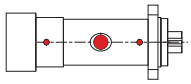
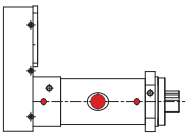
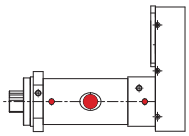
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

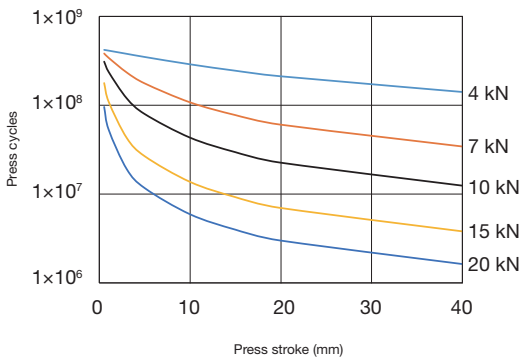
Selection Information

Basic Specifications

Ball screw lead (mm)		10
Reduction ratio		28/60
Permissible axial load[1] (kN)	Pressing direction	21.8
	Pulling direction	10.9
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		19.1
Maximum load capacity[3] (kg)		100

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

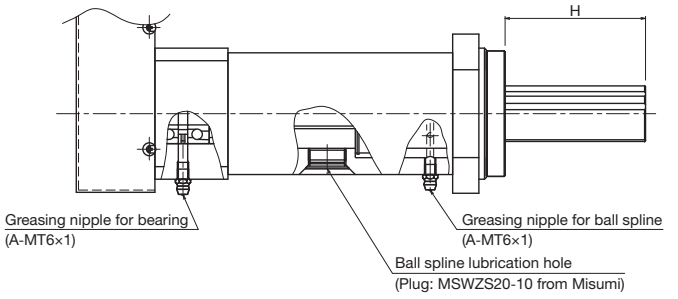


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

Maintenance

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.
Lubricate the product with the rod extended to the lubrication site.

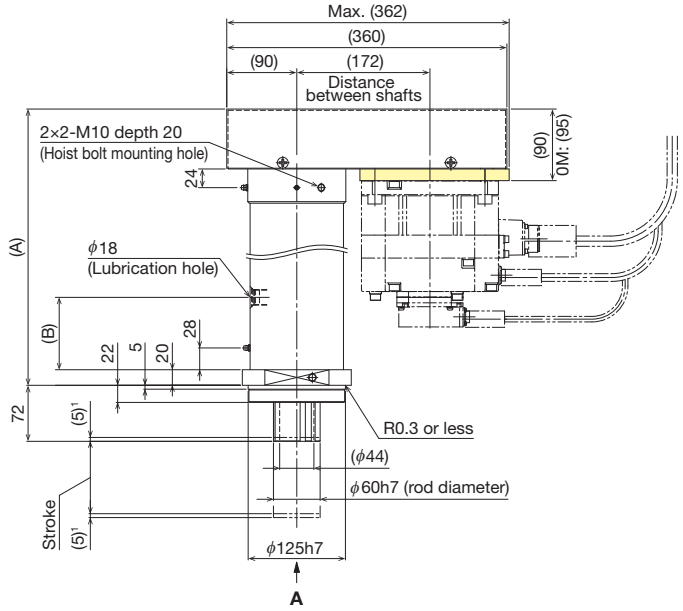


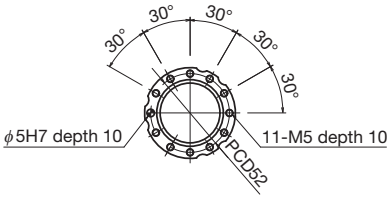
Unit: mm

Stroke	50	100	150	200	250
Lubrication site: H	91	141	191	191	191

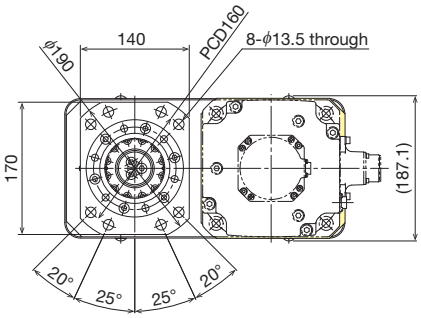
Dimensions

This figure shows lubrication site D (bottom).



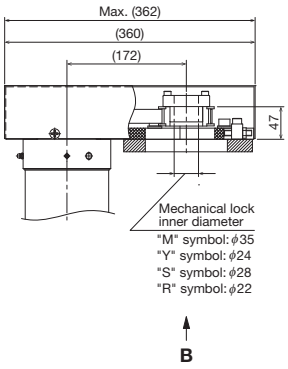


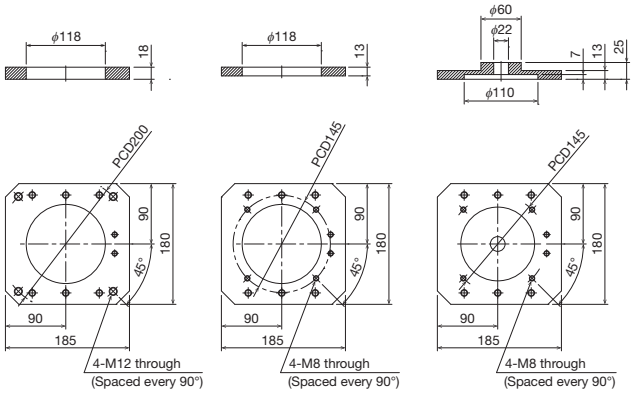
Ball spline shaft end details (view from A)



[1] This is the stroke up to the mechanical stopper.

Motor Attachment Details





Symbol: 0M | Symbol: 0Y, 0S | Symbol: 0R

View from B

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	305	355	405	455	505
	B	113			163	213
Mass[2] (kg)	0M, 0R	40.4	44	47.6	51.2	54.7
	0Y, 0S	39.3	42.9	46.5	50	53.6

[2] The final character of the symbol indicates the manufacturer. Respectively, M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; and R: OMRON Corporation.

PC60H–10F

Rod diameter 60 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Design symbol ④	Option (Lubrication Site) ⑤	Compatible motor bracket ⑥
PC60H	10F	0200	A	R	0M
PC60H	10F	0050: 50 mm	A	D: Bottom	0M: Without motor
		to		L: Left	0Y: Without motor
		0250: 250 mm		R: Right	0S: Without motor
					0R: Without motor

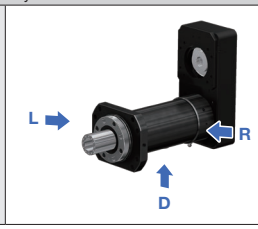
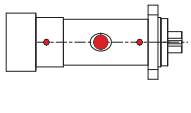
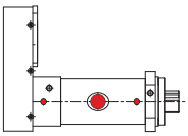
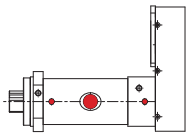
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

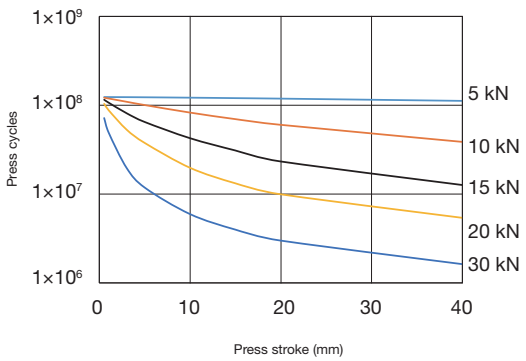
Selection Information

Basic Specifications

Ball screw lead (mm)		10
Reduction ratio		30/60
Permissible axial load[1] (kN)	Pressing direction	35.6
	Pulling direction	17.8
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		33.4
Maximum load capacity[3] (kg)		150

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

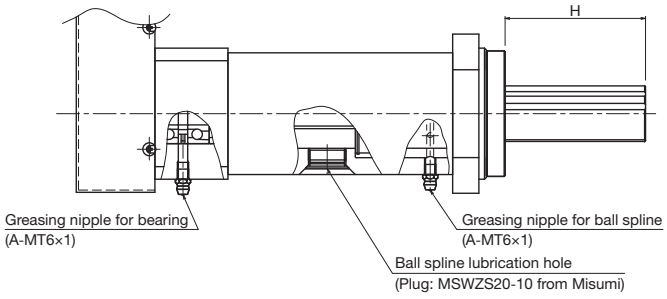


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

Maintenance

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.
Lubricate the product with the rod extended to the lubrication site.

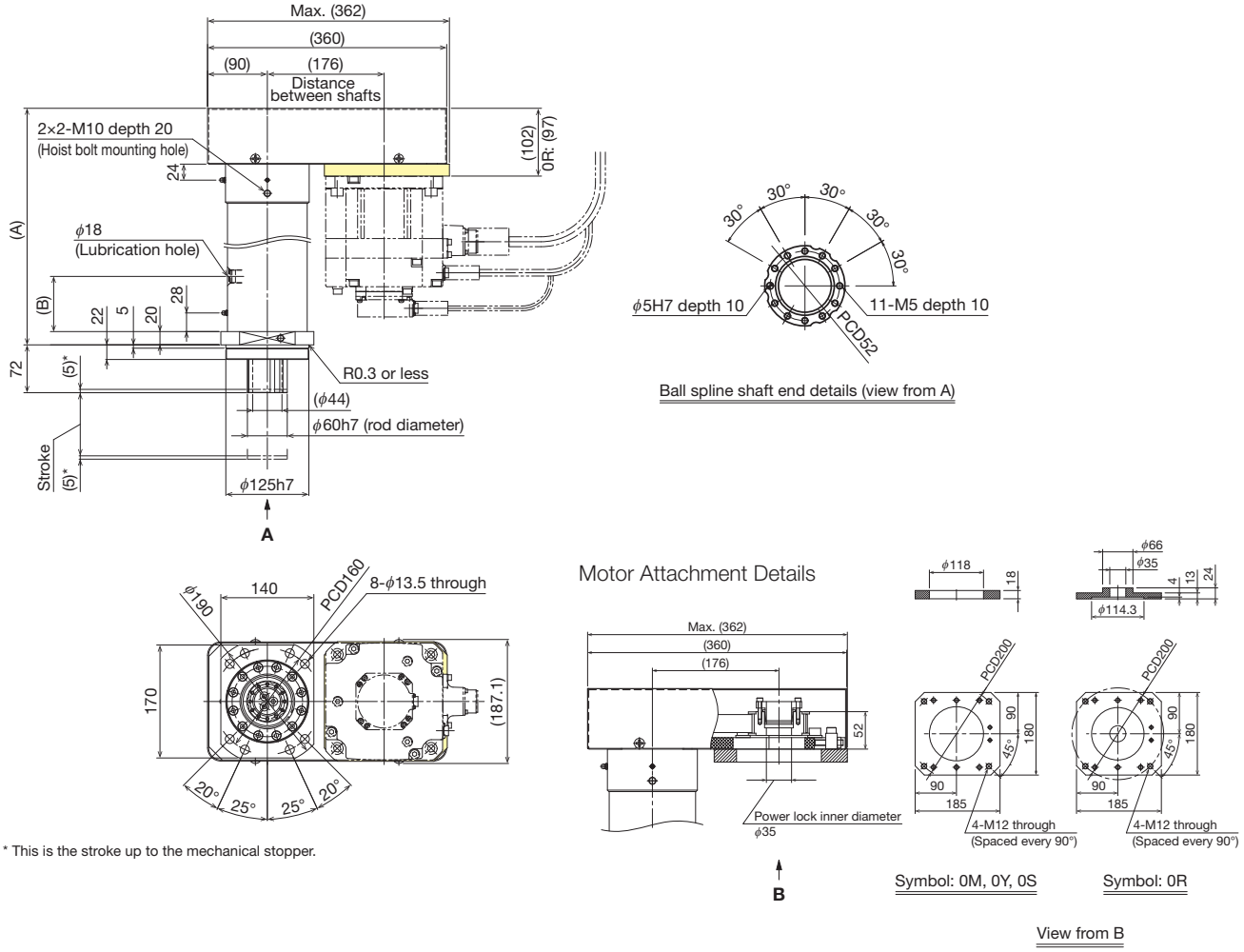


Unit: mm

Stroke	50	100	150	200	250
Lubrication site: H	100	150	200	230	230

Dimensions

This figure shows lubrication site D (bottom).



* This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	349	399	449	499	549
	B	123			145	195
Mass (kg)		44.7	48.3	51.9	55.5	59

PC80L–12G

Rod diameter 80 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Design symbol ④	Option (Lubrication Site) ⑤	Compatible motor bracket ⑥
PC80L	12G	0200	A	R	0M
PC80L	12G	0050: 50 mm	A	D: Bottom	0M: Without motor
		to		L: Left	0Y: Without motor
		0250: 250 mm		R: Right	0S: Without motor
					0R: Without motor

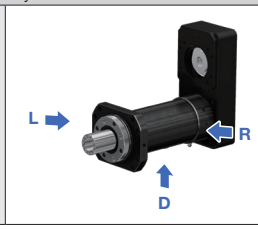
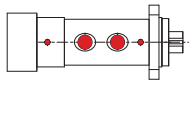
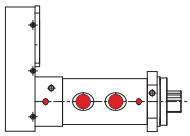
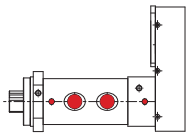
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

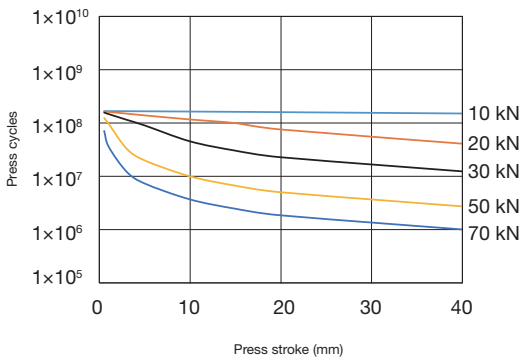
Selection Information

Basic Specifications

Ball screw lead (mm)		12
Reduction ratio		40/90
Permissible axial load[1] (kN)	Pressing direction	120
	Pulling direction	48
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		71.6
Maximum load capacity[3] (kg)		200

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

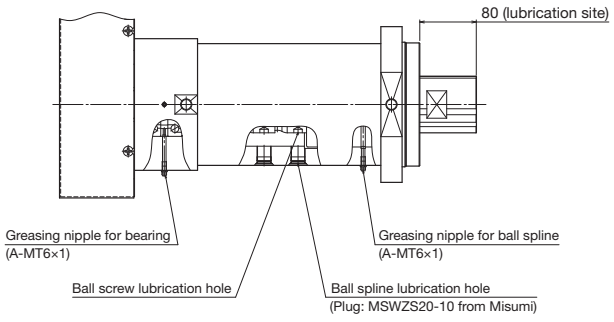


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

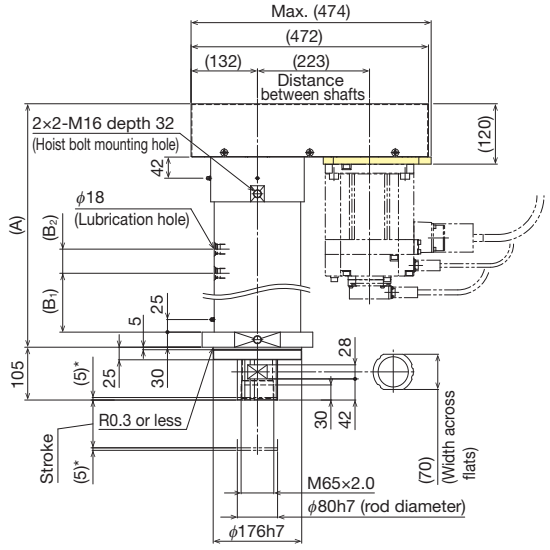
Maintenance

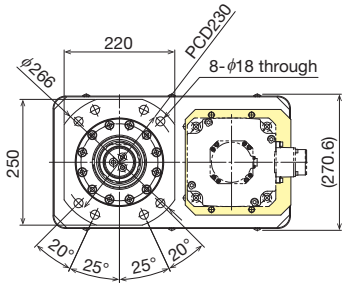
For greasing of the ball screw, remove the plug and supply grease through the ball screw lubrication hole.



Dimensions

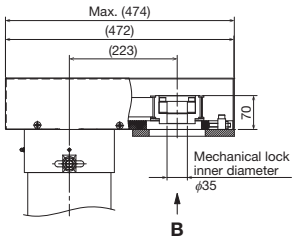
This figure shows lubrication site D (bottom).

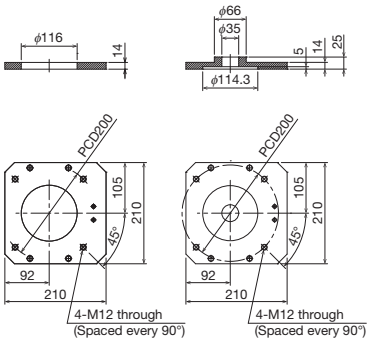




* This is the stroke up to the mechanical stopper.

Motor Attachment Details





Symbol: 0M, 0Y, 0S

Symbol: 0R

View from B

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	484	534	584	634	684
	B_1	117	119	121	171	221
	B_2	48	96	144		
Mass (kg)		118	125.2	132.5	139.8	147

PC80–12G

Rod diameter 80 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC80	–	12G	–	0200	A	–	R	–	0M
PC80		12G		0050: 50 mm	A		D: Bottom		0M: Without motor
				to			L: Left		0Y: Without motor
				0250: 250 mm			R: Right		0S: Without motor
									0R: Without motor

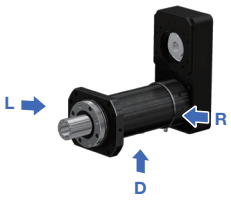
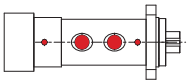
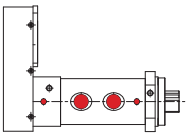
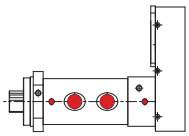
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site		Bottom	Left	Right
Symbol		D	L	R
Rough drawing of lubrication site				

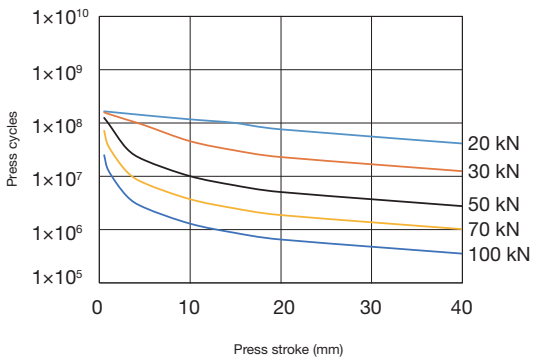
Selection Information

Basic Specifications

Ball screw lead (mm)		12
Reduction ratio		40/90
Permissible axial load[1] (kN)	Pressing direction	120
	Pulling direction	48
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		100
Maximum load capacity[3] (kg)		200

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

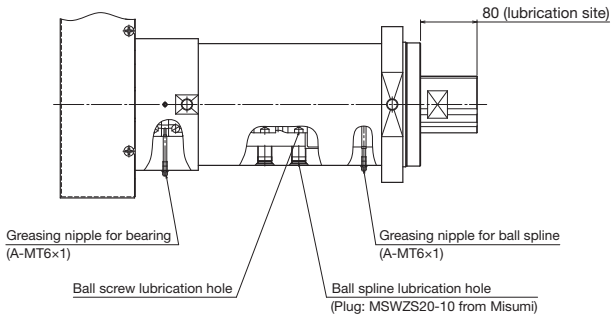


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

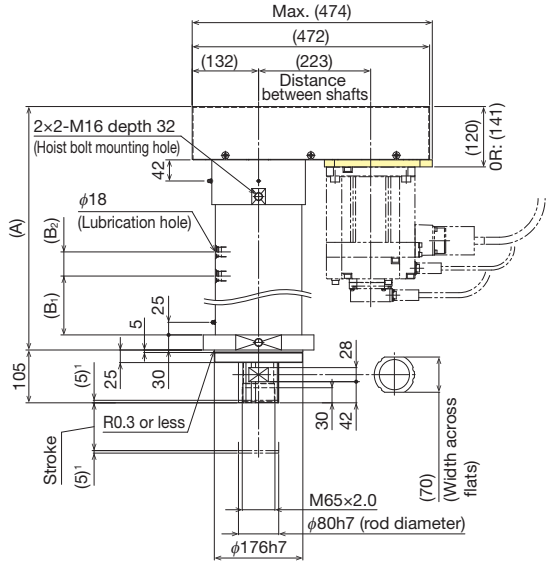
Maintenance

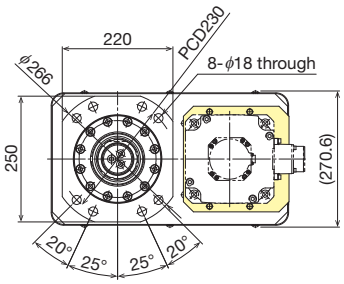
For greasing of the ball screw, remove the plug and supply grease through the ball screw lubrication hole.



Dimensions

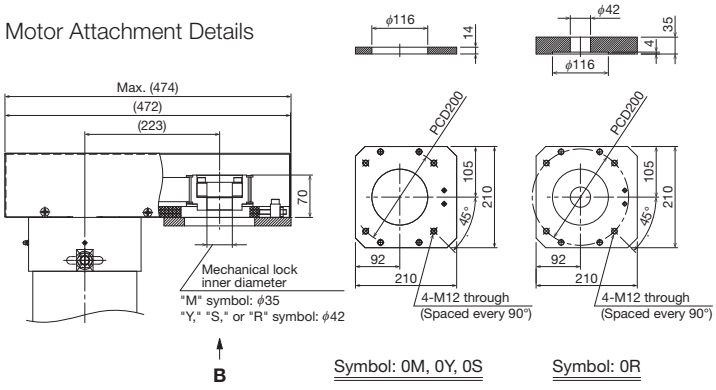
This figure shows lubrication site D (bottom).





[1] This is the stroke up to the mechanical stopper.

Motor Attachment Details



Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	484	534	584	634	684
	B_1	117	119	121	171	221
	B_2	48	96	144		
Mass[2] (kg)	0M, 0Y, 0S	117.5	124.7	132	139.3	146.5
	0R	124.7	131.9	139.2	146.5	153.7

[2] The final character of the symbol indicates the manufacturer. Respectively, M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; and R: OMRON Corporation.

PC80H–12G

Rod diameter 80 mm | Motor Wrap | Stroke max. 250 mm

Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Design symbol ④	Option (Lubrication Site) ⑤	Compatible motor bracket ⑥
PC80H	12G	0200	A	R	0M
PC80H	12G	0050: 50 mm	A	D: Bottom	0M: Without motor
		to		L: Left	0Y: Without motor
		0250: 250 mm		R: Right	0S: Without motor
					0R: Without motor

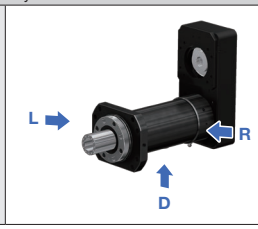
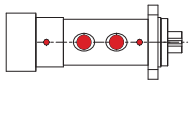
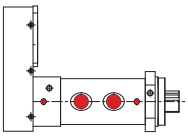
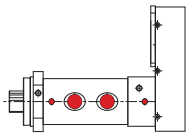
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.
R: OMRON Corporation

⑤ Option (Lubrication Site)

Lubrication site	Bottom	Left	Right
Symbol	D	L	R
Rough drawing of lubrication site				

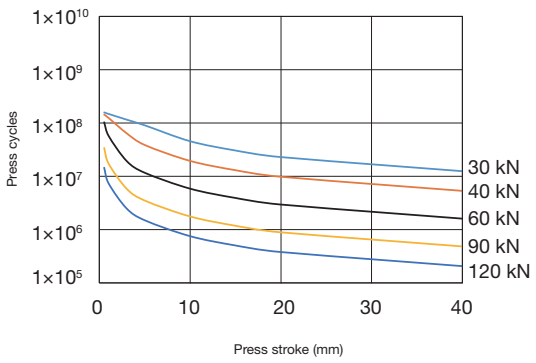
Selection Information

Basic Specifications

Ball screw lead (mm)		12
Reduction ratio		40/90
Permissible axial load[1] (kN)	Pressing direction	120
	Pulling direction	48
Positioning repeatability (mm)		±0.005
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		120
Maximum load capacity[3] (kg)		200

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 1) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

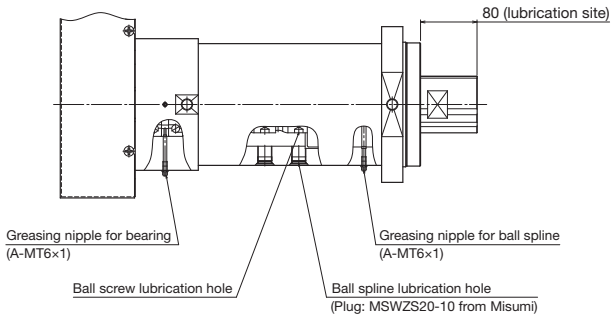


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 2) This graph is not a guarantee of press stroke operations under a press load.

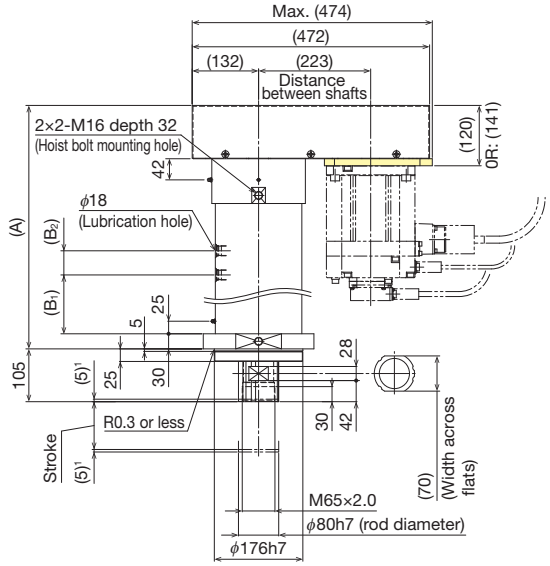
Maintenance

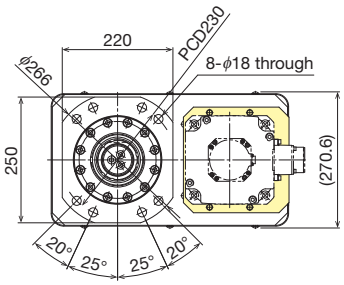
For greasing of the ball screw, remove the plug and supply grease through the ball screw lubrication hole.



Dimensions

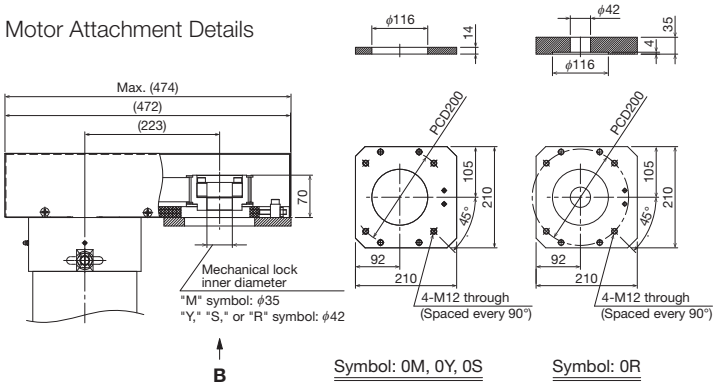
This figure shows lubrication site D (bottom).





[1] This is the stroke up to the mechanical stopper.

Motor Attachment Details



Symbol: 0M, 0Y, 0S

Symbol: 0R

View from B

Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)
Dimensions (mm)	A	484	534	584	634	684
	B_1	117	119	121	171	221
	B_2	48	96	144		
Mass[2] (kg)	0M, 0Y, 0S	117.5	124.7	132	139.3	146.5
	0R	124.7	131.9	139.2	146.5	153.7

[2] The final character of the symbol indicates the manufacturer. Respectively, M: Mitsubishi Electric Corporation; Y: YASKAWA Electric Corporation; S: SANYO DENKI CO., LTD.; and R: OMRON Corporation.

PC100–20H

Rod diameter 100 mm | Motor Wrap | Stroke max. 400 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC100	–	20H	–	0400	A	–	D	–	0M
PC100		20H		0200: 200 mm 0400: 400 mm	A		D: Bottom L: Left R: Right		0M: Without motor 0Y: Without motor 0S: Without motor

Note 1) This product will be shipped with a reduction gear installed.

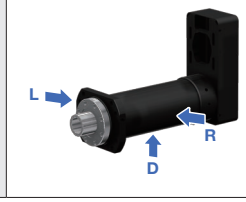
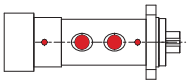
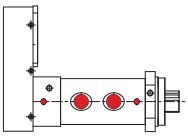
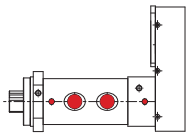
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.

⑤ Option (Lubrication Site)

Lubrication site		Bottom	Left	Right
Symbol		D	L	R
Rough drawing of lubrication site				

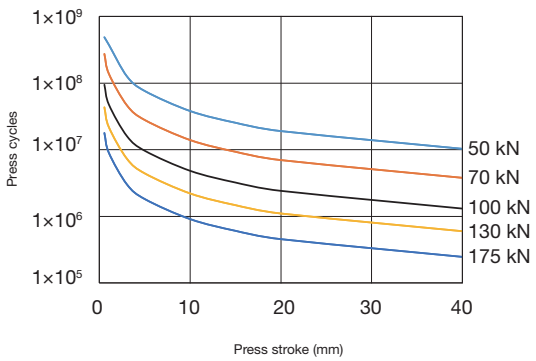
Selection Information

Basic Specifications

Ball screw lead (mm)		20
Reduction ratio (pulley ratio)		38/38
Reduction ratio (reduction gear)		1/4
Permissible axial load[1] (kN)	Pressing direction	175
	Pulling direction	70
Positioning repeatability (mm)		±0.01
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		175
Maximum load capacity[3] (kg)		200

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 2) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

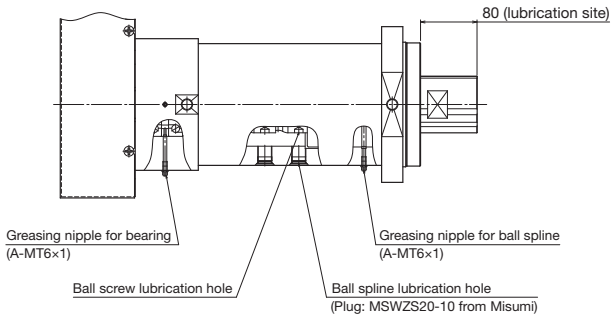


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 3) This graph is not a guarantee of press stroke operations under a press load.

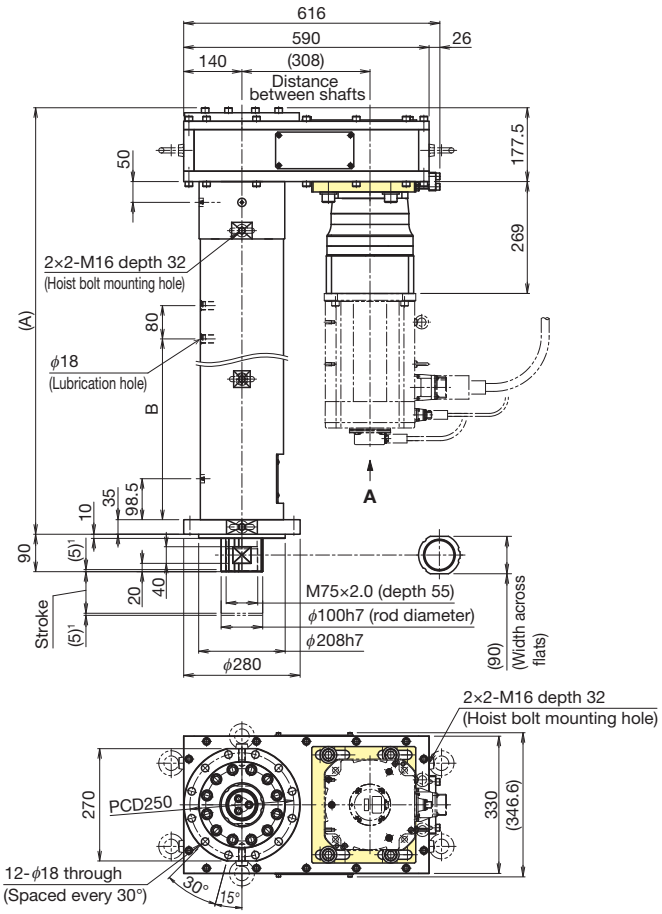
Maintenance

For greasing of the ball screw, remove the plug and supply grease through the ball screw lubrication hole.

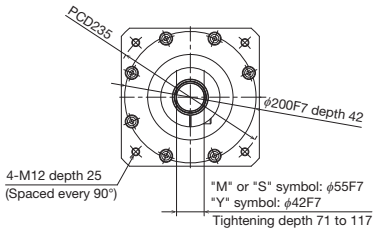


Dimensions

This figure shows lubrication site D (bottom).



Motor Attachment Details



View from A

[1] This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		200 (210)	400 (410)
Dimensions (mm)	A	825.5	1025.5
	B	251	451
Mass[2] (kg)		325	363

[2] The mass includes the reduction gear.

PC120–20J

Rod diameter 120 mm | Motor Wrap | Stroke max. 400 mm

Model Number Coding

Model ①		Lead, reduction ratio ②		Stroke ③	Design symbol ④		Option (Lubrication Site) ⑤		Compatible motor bracket ⑥
PC120	–	20J	–	0400	A	–	D	–	0M
PC120		20J		0200: 200 mm 0400: 400 mm	A		D: Bottom L: Left R: Right		0M: Without motor 0Y: Without motor 0S: Without motor

Note 1) This product will be shipped with a reduction gear installed.

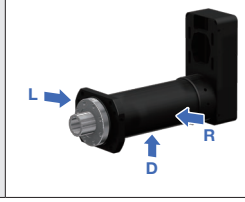
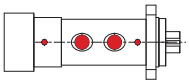
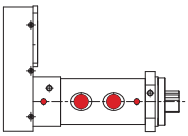
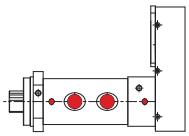
Compatible Motor Bracket Symbol Coding

0 Y

0: Without motor

Y: M: Mitsubishi Electric Corporation
Y: YASKAWA Electric Corporation
S: SANYO DENKI CO., LTD.

⑤ Option (Lubrication Site)

Lubrication site		Bottom	Left	Right
Symbol		D	L	R
Rough drawing of lubrication site				

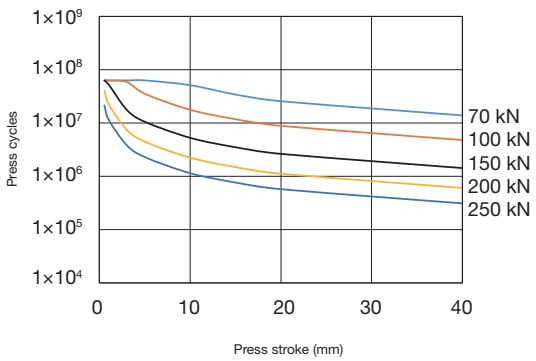
Selection Information

Basic Specifications

Ball screw lead (mm)		20
Reduction ratio (pulley ratio)		36/40
Reduction ratio (reduction gear)		1/4
Permissible axial load[1] (kN)	Pressing direction	250
	Pulling direction	106
Positioning repeatability (mm)		±0.01
Backlash (mm)		0.02
Permissible input torque[2] (N·m)		224
Maximum load capacity[3] (kg)		200

[1] The permissible axial load value shows the load that the product can bear while the actuator is stationary.
[2] There is a risk of damage to the mechanical parts. Only use the motor within the permissible input torque range.
[3] The maximum load capacity value is the mass when the product is mounted in a vertical orientation (with the rod facing down).
Note 2) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

Theoretical Press Service Life (Press Cycles)

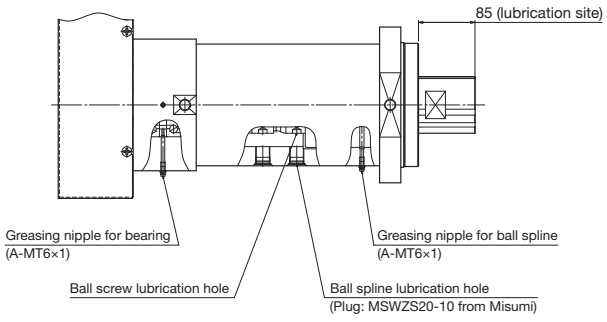


Service life will vary depending on press load and press stroke.
Operating life values are theoretical based on the below conditions.
Mounting orientation: Vertical (rod facing down)
Pressing direction: Compression direction
Load mass: Maximum load capacity

Note 3) This graph is not a guarantee of press stroke operations under a press load.

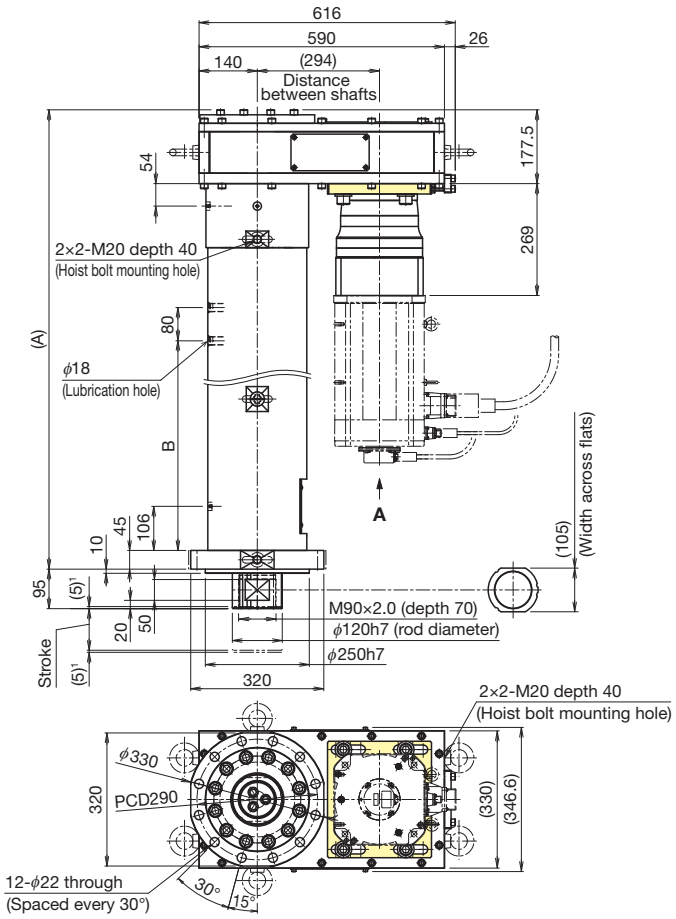
Maintenance

For greasing of the ball screw, remove the plug and supply grease through the ball screw lubrication hole.

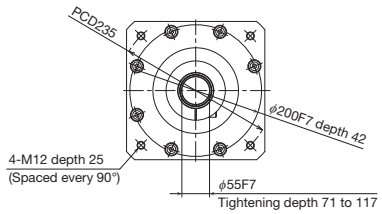


Dimensions

This figure shows lubrication site D (bottom).



Motor Attachment Details



View from A

[1] This is the stroke up to the mechanical stopper.

Stroke (mm) (Stroke between mechanical stoppers)		200 (210)	400 (410)
Dimensions (mm)	A	904.5	1104.5
	B	301	501
Mass[2] (kg)		426	480

[2] The mass includes the reduction gear.

PCT20/PCT20R

Rod diameter 20 mm | Motor Direct coupling | Motor Wrap | Stroke max. 200 mm

Model Number Coding

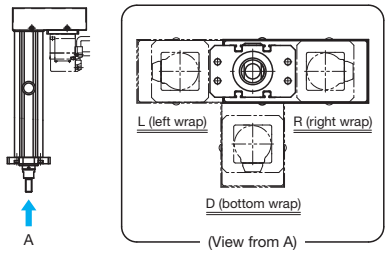
Model ①	Lead, reduction ratio ②	Stroke ③	Options ④	With/without motor ⑤	Motor bracket ⑥	Motor shaft securing method ⑦
PCT20R	06N	0200	R	0	A1	D
PCT20 PCT20R	06N	0050: 50 mm to 0200: 200 mm	With direct coupling N: Direct coupling With motor wrap D: Bottom L: Left R: Right	0: Without motor	A1 K1	With direct coupling No symbol With motor wrap D: Flat K: Key S: Clamp

"R" indicates motor wrap.

When "PCT20R" is selected for ① Model, "N" cannot be selected.

Direct motor coupling specification: No coupling will be included. Please specify if a coupling is required when ordering. Motor wrap specification: Timing pulley and timing belt will be included.

④ Option (Motor Wrap)



Motor Bracket and Motor Shaft Securing Method Compatibility

Direct Coupling

Motor type	Manufacturer	Series		Motor model	Motor rated output (W)	Motor bracket	Compatible coupling
AC servo motor	YASKAWA Electric Corporation	Σ–7		SGM7J–A5	50	A1	SFC–010DA2–6B–8B (MIKI PULLEY CO., LTD.) XGT2–19C–6–8 Nabeya Bi-tech Kaisha (NBK)
				SGM7A–A5			
		Σ–X		SGMXJ–A5			
				SGMXA–A5			
	Mitsubishi Electric Corporation	MELSERVO	J4	HG–KR053	50	A1	
				HG–MR053			
			J5	HK–KT053W			
	TAMAGAWA SEIKI CO., LTD.	TBL–iII		TS4602	50	A1	
		TBL–iIV		TSM3102			
	OMRON Corporation	OMNUC	G5	R88M–K05030	50	A1	
			1S	R88M–1M05030			
	SANYO DENKI CO., LTD.	SANMOTION R		R2□A04005	50	A1	
	Panasonic Corporation	MINAS	A6	MSMF5A	50	K1	

Motor Wrap

Motor type	Manufacturer	Series		Motor model	Motor rated output (W)	Motor bracket	Motor shaft securing method
AC servo motor	YASKAWA Electric Corporation	Σ–7		SGM7J–A5	50	A1	D, K, S
				SGM7A–A5			
		Σ–X		SGMXJ–A5		A1	D, K, S
				SGMXA–A5			
	Mitsubishi Electric Corporation	MELSERVO	J4	HG–KR053	50	A1	D, K, S
				HG–MR053			
			J5	HK–KT053W		A1	D, K, S
	TAMAGAWA SEIKI CO., LTD.	TBL–iII		TS4602	50	A1	D, K, S
		TBL–iIV		TSM3102			
	OMRON Corporation	OMNUC	G5	R88M–K05030	50	A1	D, K, S
			1S	R88M–1M05030			
	SANYO DENKI CO., LTD.	SANMOTION R		R2□A04005	50	A1	D, K, S
	Panasonic Corporation	MINAS	A6	MSMF5A	50	K1	D, K, S

Note 1) Contact THK if a motor other than the ones above will be mounted.
Note 2) The table shows only a portion of the model numbers for motors. For details regarding model numbers, please see the catalog for each respective motor manufacturer.

Selection Information

Basic Specifications

Motor rated output (W)			50
Ball screw	Screw shaft diameter (mm)		ϕ8
	Ball screw lead (mm)		6
	Basic dynamic load rating Ca (N)		1950
	Basic static load rating C0a (N)		3510
	Thread minor diameter (mm)		ϕ6.872
	Ball center-to-center diameter (mm)		ϕ8.4
Bearing (fixed side)	Axial direction	Basic dynamic load rating Ca (N)	8000
		Static permissible load P0a (N)	3240
Positioning repeatability (mm)			±0.01
Lost motion (mm)			0.1
Rod non-rotating accuracy (°)			±1
Starting torque* (N·cm)			1.6
Max. input torque (N·m)			0.48
Standard grease			THK AFB-LF Grease

* Timing pulley and timing belt are not included.
Note 3) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

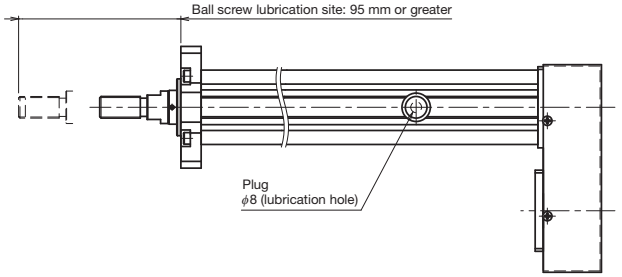
Wrapping Direction Details

Motor rated output (W)		50
Timing belt	Manufacturer	Gates Unitta Asia Company
	Model	196–2GT–6

Maintenance

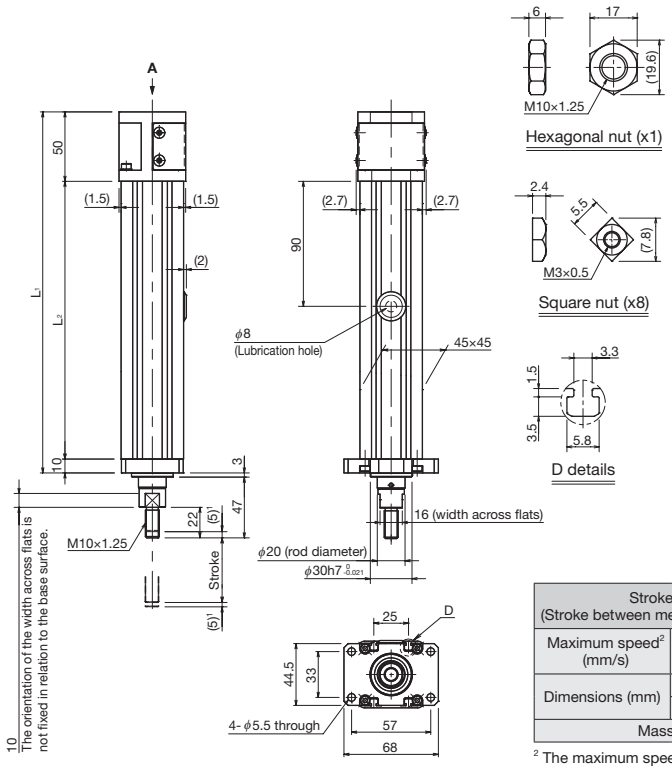
Standard grease: AFB-LF

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.



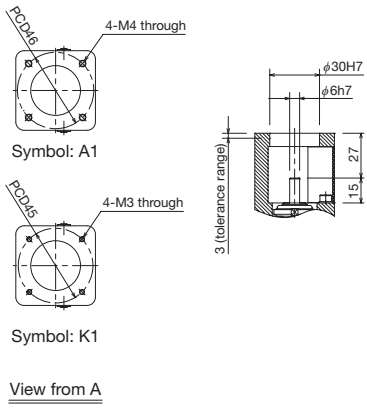
Dimensions

Direct Coupling



[1] This is the stroke up to the mechanical stopper.

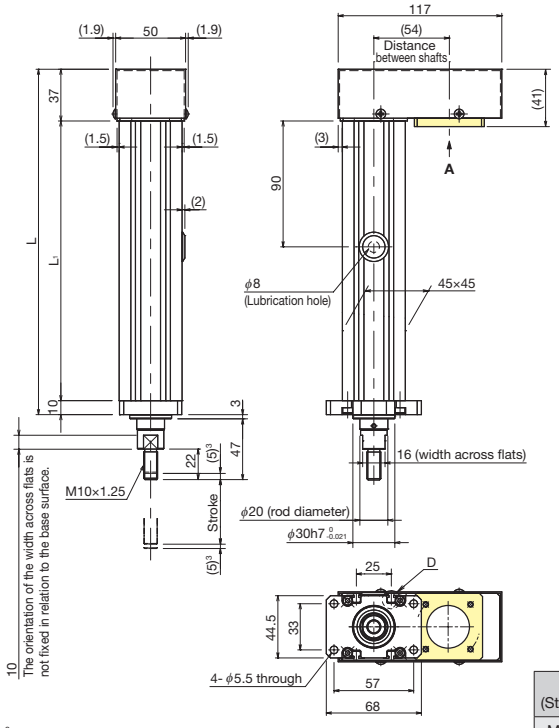
Motor Attachment Details



Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)
Maximum speed[2] (mm/s)	Ball screw lead: 6 mm	300			230
Dimensions (mm)	L_1	260	310	360	410
	L_2	200	250	300	350
Mass (kg)		1.4	1.6	1.8	2.1

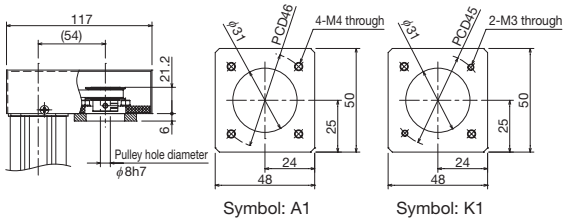
[2] The maximum speed is restricted either by the rotational speed of the motor at 3,000 min^{-1} or by the permissible speed of the actuator.

Motor Wrap



[3] This is the stroke up to the mechanical stopper.

Motor Attachment Details



Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)
Maximum speed[4] (mm/s)	Ball screw lead: 6 mm	300			230
Dimensions (mm)	L	247	297	347	397
	L_1	200	250	300	350
Mass (kg)		1.6	1.8	2	2.2

[4] The maximum speed is restricted either by the rotational speed of the motor at 3,000 min^{-1} or by the permissible speed of the actuator.

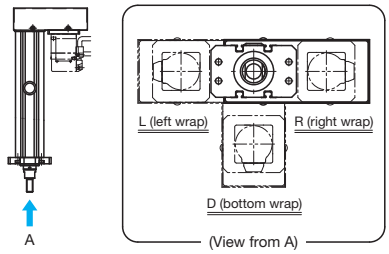
PCT25/PCT25R

Rod diameter 25 mm | Motor Direct coupling | Motor Wrap | Stroke max. 300 mm

Model Number Coding

Model ①	Lead, reduction ratio ②	Stroke ③	Options ④	With/without motor ⑤	Motor bracket ⑥	Motor shaft securing method ⑦
PCT25R –	04N –	0200 –	R –	0 –	A1	D
PCT25	04N	0050: 50 mm	With direct coupling	0: Without motor	A1	With direct coupling
PCT25R	06N	to	N: Direct coupling	Direct motor coupling specification: No coupling will be included. Please specify if a coupling is required when ordering. Motor wrap specification: Timing pulley and timing belt will be included.	A2	No symbol
“R” indicates motor wrap.		0300: 300 mm	With motor wrap		K1	With motor wrap
			D: Bottom		K2	D: Flat
			L: Left		B1	K: Key
			R: Right		B2	S: Clamp
			When “PCT25R” is selected for ① Model, “N” cannot be selected.			

④ Option (Motor Wrap)



Motor Bracket and Motor Shaft Securing Method Compatibility

Direct Coupling

Motor type	Manufacturer	Series		Motor model	Motor rated output (W)	Motor bracket	Compatible coupling
AC servo motor	YASKAWA Electric Corporation	Σ–7		SGM7J–01	100	A1	SFC–020DA2–8B–8B (MIKI PULLEY CO., LTD.) XGT2–25C–8–8 Nabeya Bi-tech Kaisha (NBK)
				SGM7A–01			
		Σ–X		SGMXJ–01			
				SGMXA–01			
	Mitsubishi Electric Corporation	MELSERVO	J4	HG–KR13	100	A1	
				HG–MR13			
			J5	HK–KT13W			
	TAMAGAWA SEIKI CO., LTD.	TBL–iII		TS4603	100	A1	
		TBL–iIV		TSM3104			
	OMRON Corporation	OMNUC	G5	R88M–K10030	100	A1	
			1S	R88M–1M10030			
	SANYO DENKI CO., LTD.	SANMOTION R		R2□A04010	100	A1	
	YASKAWA Electric Corporation	Σ–7		SGM7J–02	200	A2	SFC–025DA2–8B–14B (MIKI PULLEY CO., LTD.) XGT2–27C–8–14 Nabeya Bi-tech Kaisha (NBK)
				SGM7A–02			
		Σ–X		SGMXJ–02			
				SGMXA–02			
	Mitsubishi Electric Corporation	MELSERVO	J4	HG–KR23	200	A2	
				HG–MR23			
			J5	HK–KT23W			
	TAMAGAWA SEIKI CO., LTD.	TBL–iII		TS4607	200	A2	
		TBL–iIV		TSM3202			
	SANYO DENKI CO., LTD.	SANMOTION R		R2□A06020	200	A2	
	Panasonic Corporation	MINAS	A6	MSMF01	100	K1	SFC–020DA2–8B–8B (MIKI PULLEY CO., LTD.) XGT2–25C–8–8 Nabeya Bi-tech Kaisha (NBK)
	OMRON Corporation	OMNUC	G5	R88M–K20030	200	K2	SFC–025DA2–8B–11B (MIKI PULLEY CO., LTD.) XGT2–25C–8–11 Nabeya Bi-tech Kaisha (NBK)
			1S	R88M–1M20030			
	Panasonic Corporation	MINAS	A6	MSMF02	200	K2	
Stepper motor	ORIENTAL MOTOR CO., LTD.	α Step		AZ6*, AR6*		B1	SFC–020DA2–8B–10B (MIKI PULLEY CO., LTD.) XGT2–25C–8–10 Nabeya Bi-tech Kaisha (NBK)
		5–phase	CVK	PKP56* (this excludes PKP569FM*)		B1	SFC–020DA2–8B–8B (MIKI PULLEY CO., LTD.) XGT2–25C–8–8 Nabeya Bi-tech Kaisha (NBK)
		2–phase	PKP/CVD	PKP26*		B2	

Motor Wrap

Motor type	Manufacturer	Series		Motor model	Motor rated output (W)	Motor bracket	Motor shaft securing method
AC servo motor	YASKAWA Electric Corporation	Σ–7		SGM7J–01	100	A1	D, K, S
				SGM7A–01			
				SGM7J–02	200	A2	D, K, S
				SGM7A–02			
		Σ–X		SGMXJ–01	100	A1	D, K, S
				SGMXA–01			
				SGMXJ–02	200	A2	D, K, S
				SGMXA–02			
	Mitsubishi Electric Corporation	MELSERVO	J4	HG–KR13	100	A1	D, S
				HG–MR13			
				HG–KR23	200	A2	K, S
				HG–MR23			
			J5	HK–KT13W	100	A1	D, S
				HK–KT23W	200	A2	K, S
	TAMAGAWA SEIKI CO., LTD.	TBL–iII		TS4603	100	A1	D, K, S
				TS4607	200	A2	D, K, S
		TBL–iIV		TSM3104	100	A1	D, K, S
				TSM3202	200	A2	D, K, S
	Panasonic Corporation	MINAS	A6	MSMF01	100	K1	D, K, S
				MSMF02	200	K2	D, K, S
	SANYO DENKI CO., LTD.	SANMOTION R		R2□A04010	100	A1	D, K, S
				R2□A06020	200	A2	D, K, S
	OMRON Corporation	OMNUC	G5	R88M–K10030	100	A1	K, S
				R88M–K20030	200	K2	K, S
			1S	R88M–1M10030	100	A1	K, S
				R88M–1M20030	200	K2	K, S

Note 1) Contact THK if a motor other than the ones above will be mounted.
Note 2) The table shows only a portion of the model numbers for motors. For details regarding model numbers, please see the catalog for each respective motor manufacturer.

Selection Information

Basic Specifications

Motor rated output (W)			100		200	
Ball screw	Screw shaft diameter (mm)		ϕ14	ϕ12	ϕ14	ϕ12
	Ball screw lead (mm)		4	6	4	6
	Basic dynamic load rating Ca (N)		6600	4910	6600	4910
	Basic static load rating C0a (N)		12300	9600	12300	9600
	Thread minor diameter (mm)		ϕ11.5	ϕ9.872	ϕ11.5	ϕ9.872
	Ball center-to-center diameter (mm)		ϕ14.4	ϕ12.65	ϕ14.4	ϕ12.65
Bearing (fixed side)	Axial direction	Basic dynamic load rating Ca (N)	13800			
		Static permissible load P0a (N)	5850			
Positioning repeatability (mm)			±0.01			
Lost motion (mm)			0.1			
Rod non-rotating accuracy (°)			±1			
Starting torque[1] (N·cm)			2.8	3.2	2.8	3.2
Max. input torque[2] (N·m)			1.91 (0.95)		1.91	
Standard grease			THK AFB-LF Grease			

[1] Timing pulley and timing belt are not included.
[2] Values in parentheses are for motor wrap specifications.
Note 3) Prepare a separate guide mechanism if a load will be applied to the rod in a non-axial direction.

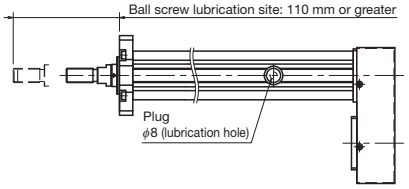
Wrapping Direction Details

Motor rated output (W)		100	200
Timing belt	Manufacturer	Gates Unitta Asia Company	
	Model	273–3GT–6	273–3GT–9

Maintenance

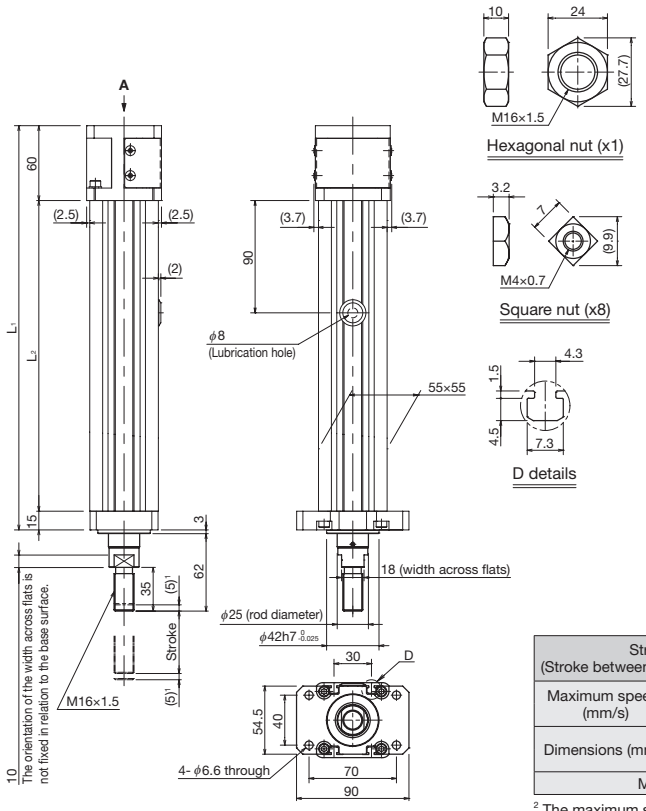
Standard grease: AFB-LF

For greasing of the ball screw, remove the plug and apply grease directly to the ball screw shaft.



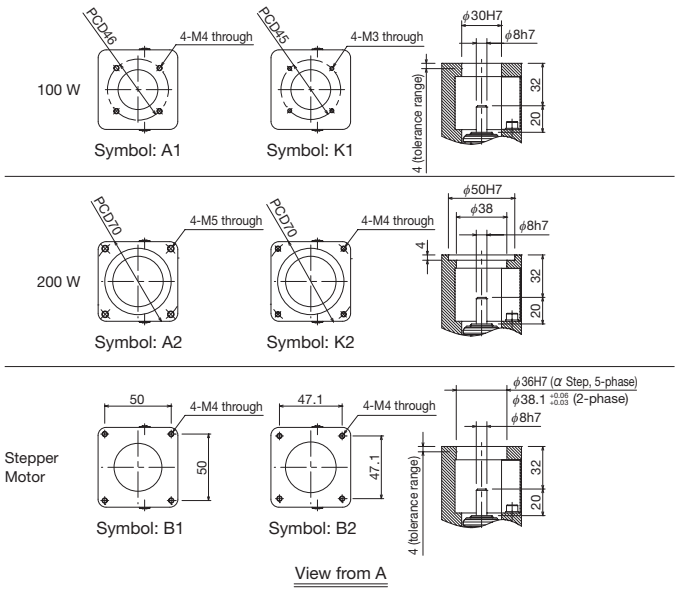
Dimensions

Direct Coupling



[1] This is the stroke up to the mechanical stopper.

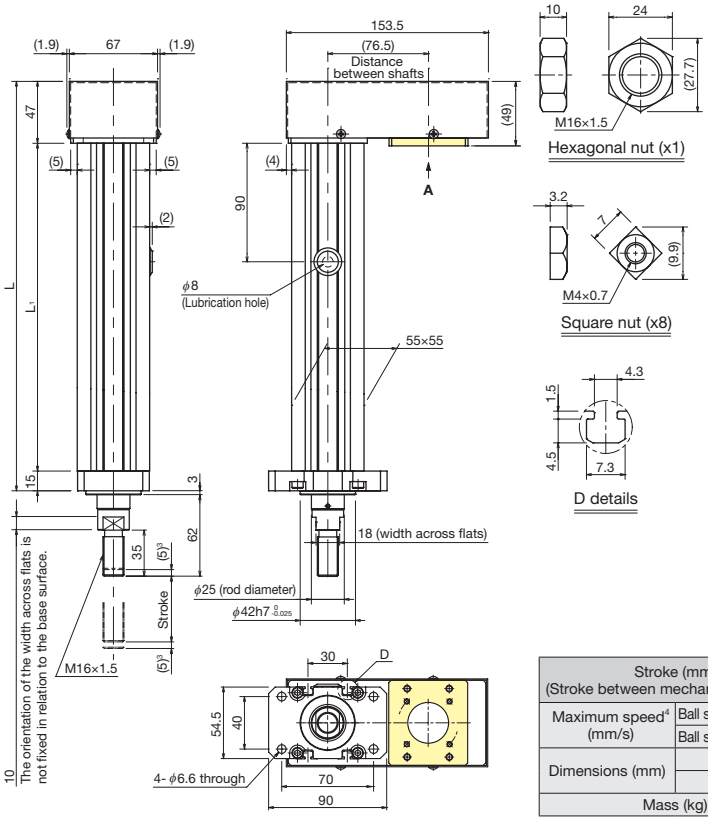
Motor Attachment Details



Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)	300 (310)
Maximum speed[2] (mm/s)	Ball screw lead: 4 mm	200				160	130
	Ball screw lead: 6 mm	300			260	200	160
Dimensions (mm)	L_1	324	374	424	474	524	574
	L_2	249	299	349	399	449	499
Mass (kg)		2.8	3.2	3.5	3.8	4.2	4.5

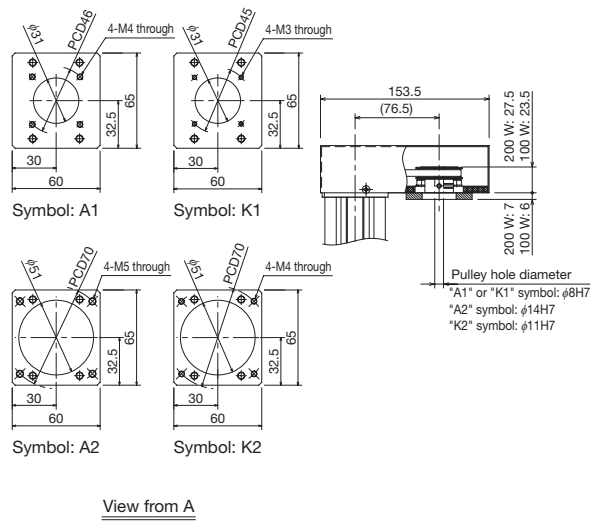
[2] The maximum speed is restricted either by the rotational speed of the motor at 3,000 min^{-1} or by the permissible speed of the actuator.

Motor Wrap



[3] This is the stroke up to the mechanical stopper.

Motor Attachment Details



Stroke (mm) (Stroke between mechanical stoppers)		50 (60)	100 (110)	150 (160)	200 (210)	250 (260)	300 (310)
Maximum speed[4] (mm/s)	Ball screw lead: 4 mm	200				160	130
	Ball screw lead: 6 mm	300			260	200	160
Dimensions (mm)	L	311	361	411	461	511	561
	L_1	249	299	349	399	449	499
Mass (kg)		3.1	3.4	3.8	4.1	4.4	4.7

[4] The maximum speed is restricted either by the rotational speed of the motor at 3,000 min^{-1} or by the permissible speed of the actuator.

MEMO

⚠Precautions on Use

How to Use this Product
· This product must not be used for devices or systems that are utilized under situations that may affect human life.
· Be sure to contact THK in advance if you are considering using this product for special applications, such as with devices or systems relating to passenger vehicles, medicine, aerospace, nuclear power, or electric power.

Products with Rotary Motor Drives

Handling
· Please contact THK when using the product in special environments such as locations exposed to constant vibrations, clean rooms, vacuums, and low/high temperatures.
· Tilting a table or outer rail may cause it to fall by its own weight.

Safety Precautions
· Carefully read JIS B8433 “Manipulating Industrial Robots - Safety” and the Japanese Ministry of Health, Labour and Welfare’s “Ordinance on Industrial Safety and Health” before working with the product, and follow the guidance within.
· Carefully read the user manual, gain a sufficient understanding of its contents, and be sure to follow the safety precautions.
· When installing, adjusting, inspecting, or performing maintenance on the main actuator unit and connected peripherals, be sure to remove all power plugs from their outlets, and prepare a lock or safety plug to prevent anyone else from turning on the power. Additionally, place a sign in a visible location to notify others that work is being performed.
· Do not touch any moving parts of the actuator while it is energized. In addition, do not enter the operating range of this product while it is in operation or in an operable state.
· If performing a task involving multiple people, confirm how to perform the work, what signals will be used, and how to handle problems before beginning, and assign another person to monitor the work.
· Do not carelessly disassemble this product. Otherwise, it may cause foreign material ingress or decrease the accuracy.
· Take care not to drop or strike this product. Otherwise, it may cause injury or damage the unit. Even if there is no outward indication of damage, a sudden impact could prevent the unit from functioning properly.
· Using this product in excess of the permissible rotational speed may damage the components or cause an accident. Please use the product within the range of speeds we have specified.
· Prevent foreign materials such as cutting chips from entering the product. Otherwise, it may damage the ball circulation components or result in a loss of functionality.
· If using the product in an environment where coolant may get inside, contact THK.
· Install shock absorbers or another impact-absorbing mechanism if there is a risk that the slider may strike the stoppers mounted on both ends of the range of motion. The stoppers are not intended to absorb the impact from sliders. Impacts to the stoppers during operation may lead to damage or accidents.
· Using this product in excess of the torque limit may damage the components or cause an accident.
· Do not set the torque control parameter higher than the torque limit.
· The motor wrap type does not have a safety device for if the timing belt breaks. For your safety, please install a safety device next to the equipment.
· The PC is designed for pressing motions. Service life will deteriorate considerably if a load is applied in the pulling direction.
· The PCT can only bear loads in the axial direction. Use in conjunction with an LM Guide so that non-axial loads will not be applied to the rod.
· If rotational torque or a moment load will be applied to the PC rod, please contact THK.
· Some models of the PC are heavy, with the main unit weighing in excess of 20 kg. When moving these products, use a hoisting belt to lift them. Use appropriate transportation equipment and take safety precautions to avoid injury or damage when transporting or assembling the product.
Do not lift this product by hooking only the hoisting belt to the main body of the unit.
When moving the product in a vertical orientation for installation, use two belts: one on the motor side and one on the rod side.
When moving the product in a horizontal orientation, use two or four belts on the motor side and rod side.
Depending on the model, the main body may tilt when hoisted due to an unbalanced center of gravity.
· In applications where this product will be moved or transferred, the conditions of use may cause inertia from the motor’s mass to result in damage to the motor attachment (Housing A) or other parts. Please contact THK before using in this manner.

Operating Environment
· Indoors, with an ambient temperature between 0°C and 40°C and ambient humidity at 20 to 80% RH (no condensation)
· A location with no corrosive or flammable gas
· A location where vibrations or impacts are not transmitted to the main unit
· A location where electrically conductive particles such as steel dust, dust, oil mist, cutting oil, water content, salt content, or organic solvents will not be present in the air
· A location not exposed to direct sunlight or radiant heat
· A location where no strong electric fields or powerful magnetic fields are generated
· A location where inspections and cleanings can easily be performed
· If this product will be used in special environments, such as one with constant vibrations, in a vacuum, or at very low or high temperatures, contact THK.

Actuator Mounting Surface
· Prepare a flat surface that has been machined or possesses an equivalent level of accuracy. Some products specify a required level of flatness.
· Be sure to mount the product on a sufficiently rigid base.

Lubrication
· The actuator must be lubricated in order for it to demonstrate its full performance. Insufficient lubrication may increase wear on the rolling elements and lead to premature damage.
· Do not mix lubricants with different properties. Please be aware that the applied lubricant will differ depending on the product.
· Contact THK if a special lubricant will be used.
· Replenish the grease every 100 km traveled under normal circumstances or 500 km under normal operation with pressure applied at one end of the stroke, or once every 6 months, whichever comes sooner. However, this will vary depending on the usage conditions, so we recommend determining the greasing interval based on the initial inspection.
· Contact THK if the product will be used in a special environment such as a location with constant vibrations, a vacuum, high/low temperatures, or a clean room, as it may not be possible to use the regular lubricant.
· Contact THK if oil lubricant will be used.
· Thoroughly wipe off anti-rust oil and feed lubricant before using the product.
· Directly apply grease to the raceway of the screw shaft, as a grease nipple is not installed on the ball screw unit.

Storage
· When storing the actuator, enclose it in a package designated by THK and store it in a horizontal orientation while avoiding high temperatures, low temperatures, and high humidity.
· Avoid storing control devices in an environment with high/low temperatures or high humidity.

Disposal
· The product should be treated as industrial waste and disposed of appropriately.

Other Recommended Products

Caged Ball LM Guide Actuator

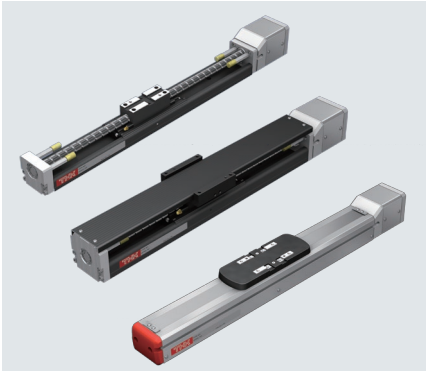
SKR

- ○ Modular structure reduces the number of parts, design hours, and assembly hours
- ○ Caged ball effect enables a long service life and long-term maintenance-free operation
- ○ Ideal for high-precision positioning and orthogonal, multi-axis designs

LM Guide Actuator

KR

- ○ Modular structure reduces the number of parts, design hours, and assembly hours
- ○ Can be used in various orientations, including horizontal, wall-mounted, vertical, and hanging
- ○ Extensive lineup of 9 sizes



LM Guide Actuator with Large-Diameter Ball Screw

KSF

Open cover/top cover/fully enclosed

- ○ Large-diameter ball screw enables high-speed and high-acceleration operations
- ○ 3 types of cover options to choose from to suit the application
- ○ Supports long strokes up to 1500 mm

Electric Cylinder **PC/PCT**

- The actual products may differ from the illustrations and photographs in this catalog.
- Outward appearances and specifications are subject to change without notice for the purpose of improvement. Please consult with THK before using.
- Although great care has been taken in the production of this catalog, THK will not take any responsibility for damages resulting from typographical errors or omissions.
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